

COMPUTER ARCHITECTURE SIMULATION
USING A REGISTER TRANSFER LANGUAGE

by

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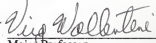
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Table of Contents

List of Figures	v
Acknowledgements	vi
1 . Introduction	1
1 .1 . Purpose of an Architecture Simulator	1
1 .2 . Instruction Set Processor	3
1 .3 . Machine Cycle Simulator	3
1 .4 . Register Transfer Language	4
1 .5 . Silicon Compilers	6
1 .6 . Definitions	8
2 . Review of Existing CHDLs	10
2 .1 . Representative CHDLs	10
2 .1 .1 . CDL	10
2 .1 .2 . ISP	11
2 .1 .3 . AHPL	11
2 .1 .4 . DDL	13
2 .1 .5 . ADLIB	14

2.1.6.	DTMS	15
2.1.7.	CONLAN	17
2.2.	Levels of Hardware Description	17
2.2.1.	Circuit Level	18
2.2.2.	Logic Gate Level	18
2.2.3.	Register Transfer Level	19
2.2.3.1.	Structure Level	19
2.2.3.2.	Functional Level	19
2.2.3.3.	Behavior Level	20
2.2.4.	Instruction Set Level	20
2.2.5.	Processor Memory Switch Level	21
2.2.6.	Algorithmic Level	21
2.3.	Applications of CHDLs	21
2.3.1.	Descriptive Tool	22
2.3.2.	Simulation and Design Verification	23
2.3.3.	Design Automation and Hardware Synthesis	24
3.	Introduction to ASIM II	25
3.1.	Purpose of ASIM II	25
3.2.	Description of Components	27
4.	ASIM II Operation	30

4.1 . Primitives	30
4.2 . Description of Primitives	31
4.2.1 . ALU	31
4.2.2 . Selector	32
4.2.3 . Memory	33
4.3 . Implementation Notes	34
4.4 . Optimization Notes	37
4.5 . Input and Output	38
5 . Conclusion	39
5.1 . Benefits	39
5.2 . Execution Speed	39
5.3 . Hardware Construction	41
5.4 . Future Considerations	42
Bibliography	45
Appendix A ASIM II Documentation	A1
Appendix B ASIM II Syntax	B1
Appendix C ASIM II Source Code	C1
Appendix D Example Stack Machine Simulator Specification (Sieve of Eratosthenes)	D1

Appendix E Pascal Code for Example Generated by ASIM II	E1
Appendix F Specification and Hardware Circuit	F1

List of Figures

Figure 3.1. Bit Concatenation.....	28
Figure 4.1. Alu specification and code generated by ASIM II.....	31
Figure 4.2. Selector specification and code generated by ASIM II.....	32
Figure 4.3. Memory specification and code generated by ASIM II.....	34
Figure 5.1. Execution time comparison of ASIM and ASIM II.....	39

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Chapter One

Introduction

1.1. Purpose of an Architecture Simulator

As computer chips have grown in complexity, the need for tools to aid the engineer in designing and testing a proposed architecture has increased greatly. Many of these tools are available as computer programs, some of which are silicon compilers, RTL (Register Transfer Language), or ISP (Instruction Set Processor). A silicon compiler deals with the actual hardware mask generation and can be quite difficult to use. ISP defines each opcode as an instruction to be executed, and thus is a one to one replacement of the assembly code to a "high level language". RTL, which is classified as a CHDL (Computer Hardware Description Language), lies between silicon compilers and ISP in terms of the level of abstraction it deals with. This thesis will concentrate on examining and using an RTL.

Using a software simulator can greatly reduce the cost of designing a new microprocessor by avoiding physical construction. This physical construction is usually more error-prone and labor intensive than a

software system due to the need to actually build the circuit under consideration. Great care must be taken to ensure that wires are hooked up correctly and that the individual chips are working properly. Also, as complexity increases, the length and type of connections becomes critical and may cause problems which are not readily apparent. Some of these problems can be ignored during the simulation phase without serious consequence; they can be dealt with during the production of a prototype. Since the project can be simulated on an existing computer, building a prototype is not necessary until later in the design phase.

In the past three years, only brief mention is made of CHDLs in the literature, partially due to manufacturers developing their own CHDL and retaining it as a trade secret [50]. In light of this, it may be quite difficult for a single CHDL to become a standard for computer architecture design, implementation, and comparison. Some of the current CHDL implementations are relatively old and are more difficult to port over to a newer and faster computer. In implementing a new CHDL, it is desirable to promote porting to other computers and to promote standardization of hardware representation at the register transfer language level. It is desirable to provide a complete set of primitives with which a designer can define a circuit.

1.2. Instruction Set Processor

ISP translates each opcode of the test architecture to an expression in a high level language where the instruction execution is often implemented as a large case structure [67]. This level of translation does not lend itself well to actual circuitry generation, but is useful in designing an instruction set for the microprocessor to execute and for simulating that execution. After the instruction set has been generated and tested, it can be converted to an RTL for further testing. The RTL provides a circuit level definition of the microprocessor.

1.3. Machine Cycle Simulator

The machine cycle simulator, a technique especially useful in microprocessor design, is somewhat related to the ISP. In addition to the capabilities of the ISP, the machine cycle simulator traces the events at each cycle, thus providing timing information not available via an ISP. This type of simulator is quite close to an RTL simulator in the type of information provided by the simulation run. However, the machine cycle simulator specification is more difficult to convert to an actual circuit than the RTL specification because it still does not represent the hardware in detail.

1.4. Register Transfer Language

RTL machine simulation is the process whereby a program written in the assembly code of the machine to be simulated is read and executed by a different machine. The result is the same as executing the code on the architecture being simulated [67]. Other forms of RTL simulation employ a machine which has characteristics that are not physically present. This virtual machine may have more memory or a different instruction set, among other characteristics.

An RTL defines the instruction set of a microprocessor for simulation in terms of a small set of register transfer statements. If the RTL statements are carefully chosen, they will remain unchanged as instruction sets are defined for various microprocessors. An RTL is not limited to microprocessors, but can also be used for almost any other piece of digital electronic hardware. This extends its usefulness beyond computer architecture to the electrical engineering field.

The basic composition of an RTL for a microprocessor is as follows. The microprocessor is defined in terms of a set of register transfers which carry out the intended function in the same way the actual microprocessor would perform it. These register transfers are a mapping of the data flow through the microprocessor. A translator then reads these instructions to simulate the proposed architecture. The actual circuitry and

the register transfer code generate exactly the same final output. In addition the register transfer execution will typically produce statistics about the actual simulation, such as execution cycles required, memory accesses, and other related information. This extra output is invaluable when the designer desires to view the internal states of a microprocessor. With the RTL model, this is easily accomplished; however, with the hardware prototype, this can be difficult or impossible due to the need to attach additional hardware to monitor the various signals.

A model of a real (or proposed) microprocessor can be defined using an RTL. Tests may be run comparing different implementations of the same languages, or of various languages. Studies of this sort could then be applied to various compilers running on this microprocessor. Comparisons could be made on execution efficiency of the compiler. In this way, a compiler writer could ascertain the statements for which the compiler has difficulty generating efficient code, and possibly deal with these inefficiencies at the RTL level. These inefficiencies can be dealt with by changing the register transfer sequences within the microprocessor to make it more closely conform to the way compilers tend to generate code. More importantly, the architecture could be changed with no hardware modifications.

1.5. Silicon Compilers

In this study, an RTL compiler written in Pascal is presented that will read the RTL specification and produce a Pascal program. This resulting program will then simulate the target architecture and produce output at each cycle of the simulation. There exists an RTL interpreter with the same input specification. The compiler written in this study generates code which executes approximately an order of magnitude faster than the current simulator. The present interpreter is used in the classroom at Kansas State University, and is too slow for use in large projects.

Silicon compilers can be used to produce a mask used in the actual production of the individual chips (microprocessor, controllers, and other specialized chips), and thus find their way into the CAD/CAM category. However, the silicon compiler is not very well suited for the testing of the design functionality of microprocessor chips. Also, the silicon compilers available today are quite inefficient both in terms of ease of use and production efficiency (in terms of physical layout of the gates on the actual chip surface) of the final chip specification [47]. An RTL is needed in the early stages of development to ease the design of the chip that actually performs the desired function.

Whereas a silicon compiler is concerned with the actual connection and layout of the gates in a chip, an RTL avoids the gate level. Since the RTL is a higher level of abstraction, a correct design is easier to build with an RTL than with a silicon compiler. Occasionally gates must be simulated in a microprocessor description, for example by saving certain internal flags or operation results in flip-flops or to describe a specific interface from memory to an ALU (Arithmetic Logic Unit). After the RTL specification has been designed and rigorously tested, the design may then be converted to a language suitable for a silicon compiler which will produce the actual layout diagrams for production.

1.6. Definitions

In simulation languages, just as in programming languages, the terms “procedural”, “nonprocedural”, “serial”, “parallel”, and “concurrent” are very common. These terms are discussed below.

In a programming language, strict timing constraints seldom need to be enforced. In contrast, for a simulation language, timing is critical to the analysis of a design. Many times the designer must know the exact cycle in which a particular event occurs so that the information can be captured and analyzed properly. Each simulated unit has a “simulation time” associated with it. The simulation time (or clock cycle) carries with

it the values of different components (registers, gates, flip-flops, etc.) corresponding to that particular simulation time.

Depending on the sequencing structure and control structure of the underlying language, a language can be classified as procedural or nonprocedural. A set of statements is procedural if the statements are executed in the same order as they are specified. This is typical of most programming languages in use today. In a nonprocedural language, the order of execution is not necessarily the same order as the statements are specified.

The terms parallel and serial are commonly used in conventional programming languages as well as CHDLs. In CHDLs the term parallel means that the actions specified are to be executed simultaneously or in the same simulation time. The term serial means one after the other. Two sequencing mechanisms exist in programming languages. **Procedural** means that the statements are executed in the same order as specified. The term **nonprocedural** refers to the absence of a sequencing mechanism. **Concurrent** means that two (or more) processes can be executing at the same time, and that any communication between the processes must be explicitly specified. The term concurrent is not synonymous with the term parallel. If statements are executed in parallel, all are executed in the same simulation time. No concept of simulation time exists in concurrent

operations. Parallel blocks are synchronous, while concurrent blocks are asynchronous. In some CHDLs, a condition is associated with each statement or statement body. In these languages, all statement bodies with a true condition are executed in a nonprocedural and parallel fashion.

Chapter Two

Review of Existing CHDLs

2.1. Representative CHDLs

A number of CHDLs have been designed to describe different levels of hardware. Each has been developed for a specific use at a certain level of abstraction. Some CHDLs lie on the border of two abstraction levels and use features from both levels, but may not be able to fully implement both levels of abstraction. The following section presents a brief review of several existing CHDLs. The levels of abstraction are described later in this chapter.

2.1.1. CDL

CDL (Computer Design Language) is an Algol-like hardware description language developed by Yaohan Chu at the University of Maryland. CDL describes the structural and functional parts of a digital system [50]. The structural components (memory, registers, clocks, and switches) are declared explicitly at the beginning of the description. The functional behavior of each element is described using operators. The

system can be described at only one level of abstraction. There is no subroutine facility in CDL, thus making it unsuitable for modular description of a system. However, its simple structure and portability (implemented in Fortran) have made CDL a popular language. The language makes use of Fortran's operators as well as user defined operators. CDL can be used to describe complex digital systems. CDL was implemented in two parts: a translator and a simulator. The translator performs a syntax check of the description and translates it into a set of tables and a polish string program. The simulator executes the output of the translator and can accept simulation parameters through the commands: LOAD, OUTPUT, SWITCH, RESET, and SIMULATE. CDL does have some drawbacks. It does not easily lend itself to hardware generation. Also, because of the nonmodular description feature of CDL and the difficulty in using the polish string output of the translator to generate logic diagram level, it is unsuitable for a Computer-Aided Design And Test (CADAT) system.

2.1.2. ISP

ISP (Instruction Set Processor), as designed by Bell and Newell, was initially intended to be used only for documentation purposes [10, 24]. Now, however, it is being used for design automation, software

generation, program verification, and architecture evaluation. ISPS (Instruction Set Processor Specifications) is a computer language based on ISP for which a compiler and simulator have been produced. ISPS is a procedural language to describe instruction sets. Since it simulates an architecture at the instruction set level, ISPS does not provide any data concerning concurrency, timing, or interconnection of processors. A user can arbitrarily stop, start, and count events during the execution of the simulator, or examine and modify the contents of registers. By comparing the results of the simulation with expected results, the user can detect errors in the design of the system. ISPS is best suited to provide performance information for a hypothetical architecture.

2.1.3. AHPL

AHPL (A Hardware Programming Language) is a procedural language developed by F. J. Hill at the University of Arizona. Like CDL, AHPL is popular and well documented [37]. AHPL has applications in three areas: documentation, design verification and automatic design. It is supported by a simulator which provides design verification. A hardware compiler provides automatic design by translating AHPL descriptions to wiring lists specifying the interconnections of gates. The principle weakness in AHPL is its difficulty to express parallelism.

2.1.4. DDL

DDL (Digital system Design Language) is a complex and powerful block oriented nonprocedural language [25]. It is based on finite state machines and is designed to describe digital systems at the boolean equation, register transfer and algorithmic levels. Many of its features are similar to CDL, but in addition it allows the design to be specified in a block oriented fashion. This allows the designer to construct a portion of the system, test it, and use that block as a module which is already debugged. These blocks are expanded to their boolean equation equivalents for actual simulation [50]. By incorporating this capability, DDL has lost some of its flexibility as a simulator. DDL is well supported by software. A translator and simulator were implemented in IFTRAN on a Harris 6024 machine. This translator converts DDL descriptions to a set of boolean equations and register transfer expressions which can be used for hardware compilation. DDL is so well documented that it is used as an instructional example in two text books [15, 23].

2.1.5. ADLIB

ADLIB (A Design Language for Indicating Behavior) is a part of the SABLE (Structure And Behavior Linking Environment) simulation and design automation system developed at Stanford University [64].

ADLIB was developed to describe the computer component types. The interconnection of the component types is specified in a separate language, SDL (Structure Design Language). This ADLIB/SABLE/SDL system is designed to describe digital systems at different levels of abstraction. This is an important feature which allows the designer to describe a subsystem, and use that description in several other places without having to replicate the description. This saves time by reducing the amount of work necessary in the description, as well as reducing the number of potential design errors. The multi-level description and simulation approach also aids in validating a lower level design. For example, a system can be described at the behavior level and also at the structure level. Both simulation results can then be compared to assure the designer of similar descriptions.

ADLIB is a superset of Pascal and thus is strongly typed like Pascal. It extends Pascal with constructs to specify synchronous and asynchronous timing, extendable data types, subprocesses and intercomponent signaling. It is well supported in software.

The strength of ADLIB is also its weakness. ADLIB works well at the behavior level, but does not work well at the structure level. Structure level simulation is an important aspect of CHDLs which are used to design a circuit for the specification.

2.1.6. DTMS

DTMS (Descriptive Techniques for Modules and Systems) was developed at Kansas State University to better describe digital systems consisting of the interconnection of complex MSI (Medium Scale Integration) and LSI (Large Scale Integration) modules [55]. Descriptions in DTMS reflect the modular hardware of modern digital systems. Module functions are described at a high behavior level, and their interconnections are specified at the structural level. These modules communicate to each other through busses. DTMS allows both procedural and nonprocedural constructs to be expressed through PROCESS and NONPROCESS sections. It is not implemented in software; instead it is intended as a documentation tool.

2.1.7. CONLAN

The development of CONLAN (CONsensus LANguage) goes back to the first Symposium on Hardware Descriptions Languages (HDL) at Rutgers University [43, 44, 45]. The lack of an industry acceptance of the dozens of HDLs then in existence prompted a team of people from the United States and Europe to develop a language in which HDLs could be standardized. There are several reasons why acceptance of existing HDLs is so low:

1. None of the languages alone is sufficient to describe all aspects of a system and cover all phases of the design process.
2. Languages of different scope are syntactically and semantically unrelated.
3. Few of the languages are formally defined.
4. Only a few languages are implemented.
5. Descriptions are represented by character strings rather than graphically.
6. There exists no complete hardware design methodology to tell how to use HDLs effectively.

The main emphasis of CONLAN is to address the first four deficiencies. CONLAN itself is not an HDL, but its primary objectives are to 1) provide a common formal syntactic and semantic base for all levels of hardware description, 2) provide a means for the derivation of user languages from this common base, and 3) support CAD tools for documentation, certification, synthesis, and so on. Although many concepts of existing CHDLs appear in CONLAN, it is not intended as a language standard, but instead is a formal system which allows designers to construct HDLs of their choice in a consistent and unambiguous way. In this way, the industry will be able to more efficiently use HDLs in the entire phase of hardware development.

2.2. Levels of Hardware Description

CHDLs have become vital in the design of microprocessors and related electronic equipment. As computers have become more complex, tools have been developed to aid the engineer in the development of the circuitry which makes up a computer system at different levels. Six levels of hardware description are widely recognized among hardware designers [50]. These are 1) circuit level, 2) logic gate level, 3) register transfer level, 4) instruction set level or programming level, 5) processor memory switch level, and 6) algorithmic level. A number of CHDLs have been developed for use at the various levels of abstraction of the design of a microprocessor.

2.2.1. Circuit Level

The components described at the circuit level are the transistors, diodes, resistors, etc. which make up the various gates of an electronic system. An electronic design is described as the interconnection of these components and is the lowest level of abstraction recognized among computer hardware designers. (There exist lower levels which are of interest to engineers who build and test these components, however, these levels are not usually used by the computer hardware developer.)

2.2.2. Logic Gate Level

The logic gate level is the description of a piece of hardware at the logic gate (AND, OR, NOT, etc.) level. Its primary purpose is to describe SSI (Small Scale Integration), MSI (Medium Scale Integration), and some LSI (Large Scale Integration) circuits. The behavior is given by a set of boolean equations, and timing is on the order of a gate delay. With the advent of VLSI (Very Large Scale Integration), the computer design engineer will have less use for this type of representation, and will need a system that begins to model the behavior of the circuit instead of the structure.

2.2.3. Register Transfer Level

The register transfer level is where most CHDLs are implemented. At this level, registers are the basic component of the system. These languages model the transfer of data between registers, and logical and arithmetic expressions. Some examples of CHDLs at this level are AHPL, DDL, and CDL. Most CHDLs operate at the register transfer level. This level has been broken down into three sub-levels [9]. These are 1) structure level, 2) function level, and 3) behavior level.

2.2.3.1. Structure Level

Structure level description consists of describing the system using actual hardware components. Operators have physical counterparts. The structure level partially corresponds to the logic gate level. The structure level can describe hardware at the logic gate level, but generally only does so when necessary. It typically uses components at a higher level of abstraction.

2.2.3.2. Functional Level

Descriptions at the functional level consist of using actual hardware components and their functional relationship rather than the connections between them. Unlike the structure level, operators do not have physical counterparts.

2.2.3.3. Behavior Level

The behavior level describes the external behavior of the system. Its purpose is to describe the algorithm used by the hardware in terms of its input and output functions. This level is similar to some of the higher levels of abstraction.

2.2.4. Instruction Set Level

ISP is an example of a CHDL at the instruction set level. At this level, the instruction set of the microprocessor is simulated. The bits that make up the program being simulated are interpreted by a specific set of rules, and results are produced based on these rules. This is a functional description of a microprocessor whereas the previous levels describe the structure of the underlying hardware. Using the instruction set level, an engineer can first develop a workable instruction set (behavior level), and then concentrate on the hardware (structure) level.

2.2.5. Processor Memory Switch Level

The Processor Memory Switch (PMS) level describes the system in terms of processing units, memory components, peripherals, and switching networks. Only the major properties of the system are defined at this level. These properties include costs, memory capacities, system peripherals, and information flow rates. One use for this level is to determine the cost effectiveness of a particular design for a microprocessor. Another use is its application as a formal feasibility study tool for the engineer.

2.2.6. Algorithmic Level

The highest level of abstraction is the algorithmic level. At this level, only the algorithm executed by the hardware is important. This is an important concept, especially considering the complexity of circuitry in modern microprocessors. The engineer can build a module using a lower level of abstraction. When the module is completed, it can be expressed as an algorithm in order to reduce the complexity of the simulator specification.

2.3. Applications of CHDLs

Most of the work in the area of CHDLs deals with the functional and behavior level of the register transfer language level. Several simulators exist on a variety of computers which operate at the functional and behavior level. The operations which define the hardware in some of these CHDLs are quite complex both in implementation and in the way they are used by the hardware engineer.

CHDLs have important applications in the computer aided design, documentation, and design automation systems. The applications fall into three main categories. These are 1) descriptive tool, 2) simulation and design verification, and 3) design automation and hardware synthesis [63]. A discussion of each application area is presented next.

2.3.1. Descriptive Tool

In any complex system development cycle, a product needs to be described before producing it, and while building and testing it. Many CHDLs are intended as a descriptive tool. Later some of these have been modified for use with the other two application areas. After describing the product, the description must be communicated to other members of the design team and documented. The efficiency of the design team's efforts can be increased with the use of a standard tool. Desirable features include a consistency check of the documentation, as well as an automated documentation revision system. As these tools become more sophisticated, they will generate additional useful information.

2.3.2. Simulation and Design Verification

Another role of a CHDL is simulation and verification. As a system is being developed, its actions can be simulated with a CHDL simulator. The simulator output can then be checked with the expected results. Since no actual hardware has been built in this phase, it is relatively easy to make a change to the design, to correct a problem or experiment with a different design. Simulating a design can also assist the engineer in verification of the design. As designs become more complex, formal proof that it will work with all possible sets of input data becomes more difficult. With the

help of a CHDL, the accuracy of a design can be tested. One way to do this is by fault injection, the process of inserting a fault in the specification to cause errors (by design) in the simulation run. Thus if a catastrophic failure occurs on a certain type of fault, additional design work is necessary to reduce the impact of the fault or reduce the chances of that kind of fault occurring.

2.3.3. Design Automation and Hardware Synthesis

Additionally, the design process and hardware synthesis needs to be automated to increase designer productivity. With a CHDL, design automation is a realistic goal. As well as providing a standard method of describing a particular system, the CHDL can be designed to produce a specification for physical construction. In many cases the hardware generated by these systems is not optimal, and may need hand optimization. However, as CHDLs become more sophisticated they will produce better specifications for the physical construction.

Chapter Three

Introduction to ASIM II

3.1. Purpose of ASIM II

Although the existing CHDLs have a large command set, a small command set which provides a maximum of functionality is most desirable. Thus it is the purpose of ASIM II (Architecture SIMulator II) to realize this goal. ASIM II (and its predecessor ASIM) has a very small command set, namely ALU, selector, and memory operations. With these three primitives, it is possible to represent nearly any hardware device. The primary advantage of the small command set is the ease of remembering the different commands. If the entire command set is easily learned by the hardware designer, a specification can be easily written without the need to consult the users manual for the description of the semantics and syntax of an exotic command utilized in certain designs. This ease of use enables the designer to use ASIM II in place of a larger language.

When writing a simulator it is important to consider that simulation at this level is very likely to take considerably more execution time than the

actual architecture would require. The machine doing the simulation as well as the machine being simulated will, of course, make a great deal of difference. Since most work will likely involve simulating relatively new architectures on an existing machine, simulation is expected to be quite slow in comparison to what the actual execution speed of the simulated device would be.

The major benefit of a RTL is to allow the circuit designer to produce a circuit using a software system to evaluate the performance characteristics of the design. Another benefit is in the classroom situation where a student will be able to use the simulator instead of or in addition to the actual hardware lab. ASIM II is motivated by the need for a simulator which would run at an acceptable speed for a significant specification. The existing simulator, ASIM, provides an acceptable degree of usefulness, but its simulation time is too slow to simulate a usable microprocessor specification. ASIM was written in Pascal by Dr. Thomas Pittman on the Macintosh computer. It was ported to a Harris computer and later to the Vax 11/780. ASIM reads the specification into tables, and produces a simulation run by interpreting the symbols in the table. ASIM II, on the other hand, produces Pascal code from the specification which is then compiled by a standard Pascal compiler and executed. The execution time

of ASIM II is less than that of ASIM by approximately an order of magnitude. This reduction is offset in part by a longer compile time.

3.2. Description of Components

The three functional units in ASIM II are 1) ALU (Arithmetic and Logic Unit), 2) Selector, and 3) Memory. These three components are sufficient to describe many different hardware projects ranging from a simple counter to a stack machine and beyond. A description of each of the components follows. See Appendix A for the formal documentation of the simulator, and Appendix B for the syntax diagrams which define the language.

The format for an ALU is:

```
A name function left right
```

where *name* is the name of the ALU, *function* is an expression which determines the operation to be performed on *left* and *right*, the two operands.

The format for a Selector is:

```
S name selector value0 value1 value2 ... valuen
```

where *name* is the name of the Selector, and the value of *selector* forms an index to the appropriate value in the value list.

The format for a Memory is:

```
M name address data operation number [initial
values]
```

where *name* is the name of the memory, *address* is the address (0 based) of the memory, *data* is the expression which gets stored in the memory (for a write operation), *operation* is the operation which is performed on the memory, *number* is the number of memory cells, and *initial values* is an optional list of values from which the memory gets its initialization data.

Most fields in the components may contain a complex expression (see Appendix B for a complete description of an expression and where the expression can occur). This expression can be composed of the concatenation of several components, and numeric constants. Thus *mem.3.4, #01, count.1* means to concatenate the fourth and fifth bits (bit positions are zero based) of *mem* with the binary string 01 and the second bit of *count* giving the result shown in Figure 3.1.

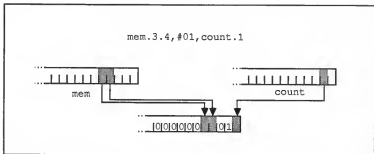


Figure 3.1 Bit Concatenation

Chapter Four

ASIM II Operation

4.1. Primitives

ASIM II has a small instruction set with which it is possible to express nearly any piece of hardware. It lacks no primitive which is needed to form a more complete command set to describe digital electronic equipment. The primitives ALU, selector, and memory have been used to describe a small stack machine which is able to execute a set of stack operators. The popular Sieve of Eratosthenes (a prime number generator implemented with a standard algorithm to assure similar test conditions among the various machines being benchmarked) has been implemented as a series of stack commands and is simulated using this simulator specification. The stack machine implementation of the Sieve of Eratosthenes is shown in Appendix D.

4.2. Description of Primitives

Each component in the specification can be replaced with a hardware component when constructing the prototype of the specification.

These hardware components can be purchased and easily connected together in the way described by the device description. A description of each primitive follows.

4.2.1. ALU

The ALU primitive is a software representation of a hardware ALU. In some cases, the ALU describes gates (NAND, AND, OR, NOT, etc.) and in other cases an actual arithmetic unit capable of addition, subtraction, multiplication, division, and comparison. Each ALU has three inputs (see Section 3.2). The function input tells the ALU which operation to perform. If the operation is a constant, the ALU may be implemented as a series of gates which perform that one function; otherwise, an actual ALU may be used, with the function bits determining its actual function. The left and right operands form the data inputs to the ALU, while the name contains the output of the ALU for use as input to another component. See Figure 4.1 for an example of an ALU specification and the code which ASIM II generates to simulate that specification. The ALU named "alu" shows the generic code generated for an ALU. The ALU named "add" shows the optimized code for a function whose value is a constant and whose function is to add the left and right operands. The

Specification:

```
A alu compute left 3048
A add 4 left 3048
```

Code generated:

```
alu := dologic(compute, left, 3048) ;
add := left + 3048;
```

Figure 4.1 ALU Specification and Code Generated by ASIM II

function `dologic` is shown in Appendix E with the code generated for the stack machine.

4.2.2. Selector

A selector is usually implemented as a data selector/multiplexor when the description is used to construct a hardware circuit. The selector input selects the input (`value0`, `value1`, ..., `valuen`) which is connected to the output. Again, the name of the selector is used to hold the output value for use as input to another component. See Figure 4.2 for an example of the code generated by ASIM II.

Specification:

```
S selector index value0 value1 value2 value3
```

Code generated:

```
case index of
  0: selector := value0;
  1: selector := value1;
  2: selector := value2;
  3: selector := value3
end;
```

Figure 4.2 Selector Specification and Code Generated by ASIM II

4.2.3. Memory

A memory is a much more complicated device. The hardware representation can be implemented in a variety of ways depending on the actual use of the memory, and the number of cells in that memory. If the memory is a single location, it will typically be represented as a flip-flop, or a set of flip-flops to hold several bits, i.e. a register. If the memory is composed of several cells, it may be represented as a ROM or RAM, depending on the type of operations that may be performed on it. Automatic logic generation of a circuit from the specification can be quite difficult if the designer wishes to have the circuit optimized to a reasonable

extent. However, the primary goal of ASIM II is to simulate a design in preparation of building a prototype. See Figure 4.3 for an example of the code generated from an ASIM II specification of a memory. (See next section for a description of the various temporary variables used.)

4.3. Implementation Notes

An ALU is implemented as a procedure call which accepts as inputs the function, left, and right operands. A case statement then decodes the function, and computes the result of the function applied to the left and right operands.

A selector, consisting of a case statement with the selector operand, provides the index to the list of cases. If the value of the selector exceeds the number of cases, a runtime error will result. It is up to the programmer to ensure that there are enough cases for the range of selector values.

Memories are implemented as a zero-based array of integers. If the number of memory locations is specified as negative, the memory is initialized with the initializer list. A memory in ASIM II, just like real hardware, has a delay from when it is accessed to when it actually provides the result of that access. This delay is one cycle.

Specification:

M memory address data operation -4 12 34 56 78

Code generated in initialization procedure:

```
memory[0] := 12;  
memory[1] := 34;  
memory[2] := 56;  
memory[3] := 78;
```

Code generated in main program:

Compute new value and handle input and output

```
case land(operation, 3) of  
  0: tempmemory := memory[address];  
  1: begin  
      tempmemory := data;  
      memory[address] := data  
    end;  
  2: tempmemory := sinut(address);  
  3: begin  
      tempmemory := data;  
      soutput(address, data);  
    end  
end; {case}
```

Figure 4.3 Memory Specification and Code Generated by ASIM II

Trace writes

```
if land(operation, 5) = 5 then  
  writeln(' Write to memory at ', address:1, ' : ',  
    tempmemory:1);
```

Trace reads

```
if land(operation, 9) = 8 then  
  writeln(' Read from memory at ', address:1, ' : ',  
    tempmemory:1);
```

Figure 4.3 (continued)

To eliminate the need for actual parallel processing of the components, the components are sorted in a dependency order. If the value of a selector requires the result of an ALU, the ALU's value is computed first, etc. Memories are not sorted. Instead, their results are stored in temporary memories (similar to the memory buffer register in actual hardware) while the new value is being computed.

The values of the components (if traced) are printed after their new values have been computed. In the case of memories, the value used in the computation is printed before it is updated with the new value it may have received during that cycle.

4.4. Optimization Notes

In implementing ASIM II, an emphasis was placed on optimization of the code produced by the compiler in an effort to reduce execution time. This optimization has a goal of reducing the number of procedure calls in the program. The generic procedure takes the function of the the ALU, and returns the value based on the three inputs, namely function, left, and right. If the function is a constant, code is generated which performs the function inline, rather than call the procedure. Similarly, if the memory operation is a constant, the case structure is eliminated and only the appropriate action is performed on the memory.

4.5. Input and Output

Input and output is possible with ASIM II, and models actual hardware designs in use today by using memory mapped I/O. Memory mapped I/O treats the input and output as a special case of memory. The I/O is received from the standard input or sent to the standard output in this simulator. ASIM II utilizes a procedure for the I/O, thus making changes in the handling of I/O easy to implement. A memory in the specification can contain the input values for execution as well. For example, the stack machine description takes its input directly from the specification. A RAM in the description contains the code which is executed. Its output is sent to

the standard output and consists of the prime numbers generated by the simulator.

Chapter Five

Conclusion

5.1. Benefits

ASIM II is an important tool for the design of a digital electronic circuit. It provides all of the necessary primitives to express nearly any circuit in a form suitable for simulation. Since the design can be simulated on a software system, actual hardware prototypes need not be built until later in the design phase. Secondly, it is a documentation tool (at a low level) useful for generating hardware that performs the function described in the specification. A team of designers can use this specification format to convey various designs to one another in a standard way.

5.2. Execution speed

The simulation time of ASIM II has been reduced significantly over that of its predecessor ASIM (see Figure 5.1). The data in Figure 5.1 was taken from the compile and execution time of the stack machine example in appendices D and E.

ASIM	
Generate tables	10.8
Simulation time	310.6
ASIM II	
Generate code	34.2
Pascal Compile	43.2
Simulation time	15.0
Traditional Methods	
Generate Prototype	100000
Run Prototype	0.01

Figure 5.1 Execution time comparison (in seconds) of ASIM and ASIM II

Both ASIM and ASIM II executed the specification for 5545 cycles (the maximum number of cycles allowable in this specification of the stack machine). The best of 5 time trials was taken with 3 of the timings taken very early in the morning to reduce the effect of other user activity causing excessive variations. ASIM uses 10.8 seconds of cpu time to prepare the tables necessary for simulation. 310.6 seconds are used in the actual simulation. ASIM II used 34.2 seconds to generate the Pascal code from the specification, and 43.2 seconds to compile the Pascal code to the object code. The simulation used only 15.0 seconds. Thus if the simulation

preparation times are not considered, (the simulator is used more often than code is generated and compiled for it) ASIM II runs approximately 20 times faster than ASIM. Including the preparation times it is nearly 2.5 times faster. This reduction has come at the cost of increased preparation time for large specifications. This includes the Pascal compile time to translate the code generated by the simulator into machine code. In contrast to the specification compile time, hand wiring of a prototype would take several days. Execution of the prototype would be so fast (real time) that monitoring states in the circuit would be difficult. However, a prototype is a necessary phase of any hardware project.

5.3 Hardware Construction

A hardware circuit can be easily built from a hardware specification in ASIM II. Essentially, ASIM II is a list of hardware components with the wiring interconnection specified by the names of the components and their bit fields. If the bit field exists in the specification, then it is known that only the particular pins corresponding to that component are hooked up to the named component. The specification is most like a block diagram of the circuit. The connections between components are not labeled with pin numbers nor actual component types. Enough information exists so that the engineer can choose appropriate

components which perform the function of the specified component. See Appendix F for an example of a hardware specification and circuit for a small 10 bit microprocessor with five instructions (load, store, branch, branch on borrow, and subtract) and 128 bytes of program and data memory. Note that each of the components in the specification has a hardware component represented in the diagram. It should be noted that this is not an optimum circuit, but rather a reflection of the ASIM II specification and demonstrates the ease of translating the specification to an actual hardware circuit. Actual hardware generation is beyond the scope of this thesis, however, it is appropriate to show a small example to demonstrate the value of ASIM II for larger projects.

5.4. Future Considerations

The ALUs, selectors, and memories provide a slightly higher level of abstraction than most other CHDLs provide. This makes hardware description somewhat more modular in that the lower level primitives such as gates are not expressed unless they are necessary in the description. Thus, a complete description is smaller in ASIM II than in most of the other CHDLs.

As with all software, there is always room for improvement. Further optimization of the code is possible using heuristics to determine

which memories do not need temporary variables in which to store results while the new values are computed for the memories.

Modularity is an important concept in today's programming languages. ASIM II, however, does not have any high level modularity construct. The behavior of an electronic circuit is difficult to express in a modular fashion without providing the the actual description of the module and expanding that description at compile time. As semiconductor prices continue to fall and microprocessors gain more features, modularity will become more important. The designer will be less concerned over the amount of silicon required for the circuit than the additional time needed to produce a specification with fewer gates (typically less modular due to the gate reduction techniques).

ASIM II has become a valuable tool for small digital hardware projects. With improved speed, and modularity, it could become even more useful for simulating hardware components at the behavior and structure levels.

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Appendix A

ASIM II Documentation

To invoke ASIM II, type `sim [file]`. If `file` is not specified, you will be prompted for an input file. `File` contains the specification to be compiled. After successful compilation, type `pc simulator.p` in order to generate executable code (`a.out`) from the specification.

File format:

The first line must be a comment line starting with the '#' character. This line is echoed to the code file as a comment. Any number of macros may follow. A macro begins with a '~' and is followed by a name, followed by a text string which will be substituted for the macro name in the definition of components. (No whitespace between '~' and name, and no whitespace in macro string). A macro may be placed anywhere in an expression as long as the macro string can legally replace the macro name. The macro name is entered in the component specification with a '~' immediately followed by the macro name, and may be part of any string. Any character except letters and numbers will delimit a macro name from

the rest of the string. A macro may contain a macro name, as long as that name has already been defined (cannot be circular or recursive).

The number of cycles the simulator is to run can, but need not be specified. The format is an '=' sign followed by a decimal integer. (Whitespace between '=' and integer). If the number of cycles is not specified, you will be asked how many cycles to execute at the beginning of the simulation. After those cycles have been executed, you will again be prompted for the cycle number to continue to.

A list of all component names follows with an '*' immediately following each name that is to be traced at each cycle. A period ends the list of names. The names may be listed in any order. Those followed by an '*', will be printed in the order listed. The component specification follows the list of names. Components consist of ALUs (A), Selectors (S), and Memories (M), and may appear in any order. The components will be sorted to resolve any dependencies. Circular dependencies will generate an error message providing a clue to the component(s) which are involved in the dependency. Following is a list of the components:

```
A name function left right
S name address value0 value1 ... valuen
M name address data operation number [value0 value1
... valuen]
```

It is up to the user to provide enough values for all possible address values in a selector. Otherwise a runtime error will result. If `number < 0` then the memory is initialized with the values listed. The specification must end with a period.

Notes:

Fields must not contain whitespace. Comments may be placed anywhere in the file where whitespace is permitted. A comment starts with a '{' and ends with a '}'. Nested comments are not supported. A runtime error will occur if the number of sources for the selector is less than the value of the address, or if a memory address falls outside the declared range which starts at 0. If the number in memory is less than zero, then there must be exactly that many initial values provided. All components are initialized to zero before simulation begins (except memories with initial values listed).

I/O Memory operations take the memory data from standard input, or send the memory data to standard output, depending on the read/write bit. If the address (for both read and write) is 0, then the data is treated as character data, if the address is 1, the data is treated as an integer, otherwise the data is treated as an integer, and the address read or written is

printed. These input and output functions are handled as a procedure in ASIM II, and may be modified by the user if some other action is desired.

Below is a list of ALU functions and memory operations

ALU functions:

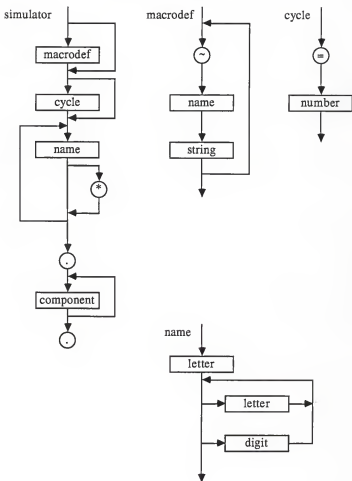
- 0 0
- 1 right
- 2 left
- 3 NOT(left)
- 4 left + right
- 5 left - right
- 6 left * 2^{right} (shift left)
- 7 left * right
- 8 AND(left, right)
- 9 OR(left, right)
- 10 XOR(left, right)
- 11 unused
- 12 left = right
- 13 left < right

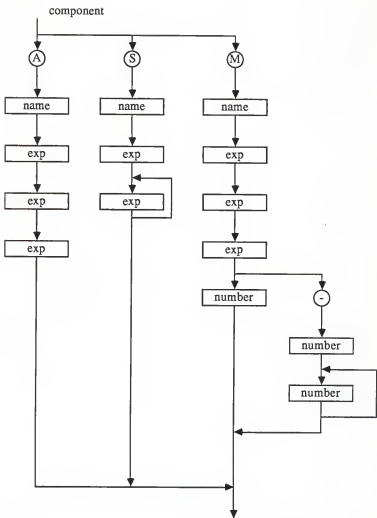
Memory operations:

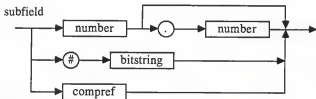
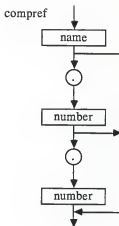
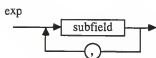
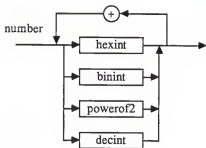
- 0 read
- 1 write
- 2 input
- 3 output
- 4 trace writes
- 8 trace reads

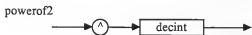
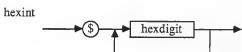
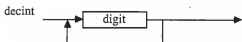
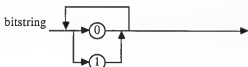
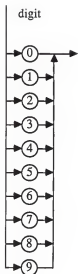
Functions 12 and 13 evaluate to 1 if true, 0 if false.

Appendix B ASIM II Syntax

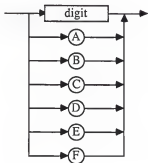








hexdigit



Appendix C

ASIM II Source Code

```

(*****)
(*)
(*) Author:          Lester Bartel
(*) Program name:    ASIM II
(*) Date completed:  7 October 1986
(*)
(*) Description:     ASIM II is an architecture simulator that
(*) reads an input description from a file and produces
(*) Pascal code which will simulate the specification.
(*) If an error occurs in the specification, the code
(*) generation ceases, and an error is reported describing
(*) the error condition.
(*)
(*)
(*****)

program simulator(input, output);

label
  1;

const
  strsize = 127; {max length of string}
  maxcomponents = 500; {max number of components}

type
  charset = set of char;
  string = array[0..strsize] of char;
  kindtype = (alu, sel, mem);
  caseptr = ^casetype;
  casetype = record
    casevalue: string;
    link: caseptr
  end; {record}
  valueptr = ^valuetype;
  valuetype = record
    value: integer;
    link: valueptr
  end; {record}
  nameptr = ^nametype;
  nametype = record

```

```

    name: string;
    print, used: boolean;
    link: nameptr
end; {record}
compptr = ^comptype;
comptype = record
    used: boolean;
    name: string;
    link: compptr;
case kind: kindtype of
    alu: (funct, left, right: string);
    sel: (select: string;
          cases: caseptr);
    mem: (addr, data, opn: string;
          number: integer;
          values: valueptr)
end; {record}
macroptr = ^macrotype;
macrotype = record
    name, macro: string;
    link: macroptr
end; {record}

var
    token, filename, comment: string;
    ch: char;
    donereading, err, varflag, endmacrodef, gettokenend: boolean;
    inf, sim: text;
    numbers, hexnums, letters, whitespace: charset;
    numcomponents, numcycles, i: integer;
    nametable, nptr: nameptr;
    comptable, ptr: compptr;
    macrotable: macroptr;
    highbits: array[0..31] of integer;

function length (a: string): integer;
{*****}
(*
(* This function returns the length of the string passed in. *)
(*
{*****}
begin
    length := ord(a[0])
end; {length}

```

```

procedure concat (var a: string; b: string);
(*****)
(*
(* This procedure concatenates the string b to the end of
(* string a, returning the string a.
(*
(*
(*****)

var index, lena, lenb: integer;
begin
    lena:= length(a);
    lenb:= length(b);
    if lena + lenb > strsize then
        lenb:= strsize - lena;
    a[0] := chr(lena+lenb);
    for index := 1 to lenb do
        a[lena+index]:= b[index]
end; (concat)

procedure concat1 (var a: string; b: char);
(*****)
(*
(* This procedure concatenates the character b to the end of
(* the string a returning the string a.
(*
(*
(*****)

begin
    if length(a) < strsize then a[0] := chr(length(a)+1);
    a[length(a)] := b
end; (concat1)

function strcmp (str1, str2: string): boolean;
(*****)
(*
(* This function compares the two strings passed to for
(* equality. It returns a boolean value.
(*
(*
(*****)

var i, len1: integer;
begin
    if length(str1) <> length(str2) then
        strcmp := false
    else begin
        i := 1;
        len1 := length(str1);
        while (str1[i] = str2[i]) and (i < len1) do
            i := i + 1;
        if str1[i] = str2[i] then

```

```

        strcmp := true
    else
        strcmp := false
    end; (if)
end; (strcmp)

procedure swrt (var fil: text; a: string);
(*****)
(*
(* This procedure prints the string a to the file fil.
(*
(*
(*****)

var i: integer;
begin
    for i:= 1 to length(a) do
        write(fil, a[i]);
    end; (swrt)

function max(a, b: integer): integer;
(*****)
(*
(* This function returns the largest of a and b.
(*
(*
(*****)

begin
    if a > b then
        max := a
    else
        max := b
    end; (max)

procedure printcomperr;
(*****)
(*
(* This procedure prints the last component read in. It is
(* used to report which component caused an error condition.
(*
(*
(*****)

var ptr: compptr;
begin
    if not donereading then begin
        ptr := comptable;
        while ptr^.link <> nil do
            ptr := ptr^.link;
            write('Last component read is <');
            swrt(output, ptr^.name);
            writeln('> (error is in this or the next component).');

```

```

    end; {if}
end; {printcomperr}

function numberofbits(str: string): integer;
(*****
(*
(* This function returns the number of bits represented by
(* the expression in str. It is used for code optimization.
(*
(*
(*****)
var i, n, m: integer;
begin
    n := 0;
    m := 0;
    i := 1;
    while (i <= length(str)) and (n < 31) do begin
        if str[i] in ['#', '#'] then begin
            i := i + 1;
            m := 0;
            while (i <= length(str)) and (str[i] in ['0', '1'])
            do begin
                m := m + 1;
                i := i + 1;
            end; {while}
            if str[i] <> '.' then
                n := n + m
            else begin
                i := i + 1;
                m := 0;
                while (str[i] in numbers) and (i <= length(str)) do begin
                    m := m * 10 + ord(str[i]);
                    i := i + 1;
                end; {while}
                n := n + m;
            end; {if}
        end {if #}
        else if (str[i] = '$') or (str[i] in numbers) then begin
            i := i + 1;
            while not(str[i] in ['.', ',']) and (i <= length(str)) do
                i := i + 1;
            if (str[i] = '.') and (i <= length(str)) then begin
                m := 0;
                i := i + 1;
                while (str[i] in numbers) and (i <= length(str)) do begin
                    m := m * 10 + ord(str[i]);
                    i := i + 1;
                end; {while}
                n := n + m;
            end
        end
    end
end

```

```

else
  n := 31
end (if $)
else if str[i] = '^' then begin
  i := i + 1;
  m := 0;
  while (str[i] in numbers) and (i <= length(str)) do begin
    m := m * 10 + ord(str[i]);
    i := i + 1;
  end; (while)
  n := max(n, m + 1)
end (if ^)
else if str[i] in letters then begin
  i := i + 1;
  while ((str[i] in letters) or (str[i] in numbers)) and
    (i <= length(str)) do
    i := i + 1;
  if (str[i] = '.') and (i <= length(str)) then begin
    m := 0;
    i := i + 1;
    while (str[i] in numbers) and (i <= length(str)) do begin
      m := m * 10 + ord(str[i]);
      i := i + 1
    end; (while)
    if (str[i] = '.') and (i <= length(str)) then begin
      n := n - m;
      m := 0;
      i := i + 1;
      while (str[i] in numbers) and (i <= length(str)) do begin
        m := m * 10 + ord(str[i]);
        i := i + 1
      end; (while)
      n := n + m + 1
    end (if)
  else
    n := n + 1
  end (if)
else
  n := 31
end; (if letters)
i := i + 1;
end; (main while)
if n > 31 then
  n := 31;
  numberofbits := n
end; (numberofbits)

```

```

function str2num (a: string): integer;
(*****)
(*                                     *)
(* This function returns the integer equivalent of the string *)
(* passed to it. The string may consist of the summation of *)
(* any combination of numbers as defined in the syntax chart. *)
(*                                     *)
(*****)

var i, j, k, l, m, len: integer;
begin
  j := 0;
  i := 1;
  len := length(a);
  while i <= len do begin
    if (a[i] in numbers) or (a[i] in ['^', '$', '%']) then begin
      case a[i] of
        '0', '1', '2', '3', '4', '5', '6', '7', '8', '9' : begin
          k := 0;
          while (a[i] in numbers) and (i <= len) do begin
            k := k * 10 + ord(a[i]) - ord('0');
            i := i + 1;
          end; {while}
          j := j + k;
        end; {case numbers}
        '%' : begin
          k := 0;
          i := i + 1;
          while (a[i] in ['1', '0']) and (i <= len) do begin
            k := k * 2;
            if a[i] = '1' then k := k + 1;
            i := i + 1;
          end; {while}
          j := j + k;
        end; {case %}
        '$' : begin
          k := 0;
          i := i + 1;
          while (a[i] in hexnums) and (i <= len) do begin
            k := k * 16;
            if a[i] in numbers then
              k := k + ord(a[i]) - ord('0')
            else
              k := k + ord(a[i]) - ord('A') + 10;
            i := i + 1;
          end; {while}
          j := j + k;
        end; {case $}
        '^' : begin
          k := 0;

```

```

        i := i + 1;
        while (a[i] in numbers) and (i <= len) do begin
            k := k * 10 + ord(a[i]) - ord('0');
            i := i + 1
        end; {while}
        l := l;
        for m := 1 to k do
            l := l * 2;
        j := j + 1;
    end (case ^)
end; {case}
if (i <= len) and (a[i] <> '+') then begin
    write('Error. Malformed number ');
    swrt(output, a);
    writeln('.');
    err := true;
    printcomperr;
    goto 1
end
end
else begin
    write('Error. Malformed number ');
    swrt(output, a);
    writeln('.');
    err := true;
    printcomperr;
    goto 1
end; {if}
i := i + 1
end; {while}
str2num := j
end; {str2num}

function numeric (str: string): boolean;
(*****)
(*
    *
    * This function determines if the expression passed in as
    * string is a numeric constant. It is used for optimization.
    *
    *)
(*****)

var i: integer;
begin
    numeric := true;
    for i := 1 to length(str) do
        if not (str[i] in ['+', '%', '$', '^', '0'..'9', 'A'..'F']) then
            numeric := false
    end; (numeric)

```

```

function land (a, b: integer): integer;
(*****
*)
*) This function performs the bit and function on the values *)
*) of a and b. *)
*)
*)
(*****)

type bitnos = 0..31;
      bigset = set of bitnos;
var intset: record case boolean of
      false: (i, j: integer);
      true: (x, y: bigset)
      end;

begin
with intset do begin
  i := a;
  j := b;
  x := x * y;
  land := i
end
end {land};

function findname (name: string): compptr;
(*****
*)
*) This function finds the component name and returns a *)
*) pointer to it. *)
*)
*)
(*****)

var ptr: compptr;
begin
  findname := nil;
  ptr := comptable;
  while (ptr <> nil) do begin
    if strcmp(ptr^.name, name) then findname := ptr;
    ptr := ptr^.link
  end; {while}
end; {findname}

```

```

procedure expr(str: string; tempflag: boolean);
(*****)
(*
(* This procedure generates the Pascal code for the expr in *)
(* str. If tempflag is true, it generates code for the *)
(* temporary values for the memories. Otherwise, code is *)
(* generated using the subscripted memory value. The str *)
(* may be any valid expression derivable from the syntax *)
(* diagrams. *)
(*
(*****)

var fptr: compptr;
    a, b, name: string;
    i, j, k, l, m, n, o, p, q, frombit, tobit, bits, numbits,
    consttotal: integer;
    fromflag, toflag, addflag, dirtyflag: boolean;
begin
    i := length(str);
    j := i;
    numbits := 0;
    consttotal := 0;
    addflag := false;
    dirtyflag := false;
    repeat
        while (i>0) and (str[i] <> ',') do
            i := i - 1;
        l := i;
        a[0] := chr(j - i);
        for k := i+1 to j do
            a[k-1] := str[k];
        if a[l] in ['$ ', '%', '^', '0'..'9'] then begin {number}
            m := 1;
            while (m <= length(a)) and (a[m] <> '.') do begin
                b[m] := a[m];
                m := m + 1;
            end; {while}
            b[0] := chr(m - 1);
            q := 0;
            o := str2num(b);
            if (a[m] = '.') and (m <= length(a)) then begin
                m := m + 1;
                n := m;
                while m <= length(a) do begin
                    b[m - n + 1] := a[m];
                    m := m + 1;
                end; {while}
                b[0] := chr(length(a) - n - 1);
                for p := 1 to str2num(b) do
                    q := q + highbits[p];
            end;
        end;
    until (i = 0) or (tempflag);
end;

```

```

consttotal := consttotal + land(o, q) * highbits[numbits];
numbits := numbits + str2num(b)
end
else begin
  consttotal := consttotal + o * highbits[numbits];
  numbits := 31
end {if}
end {case numbers}
else if a[l] = '#' then begin {binary string}
  a[l] := '%';
  consttotal := consttotal + str2num(a) * highbits[numbits];
  numbits := numbits + length(a) - 1
end {case #}
else if a[l] in ['a'..'z', 'A'..'Z'] then begin
  {component reference}
  dirtyflag := true;
  fromflag := false;
  toflag := false;
  frombit := 0;
  tobit := 0;
  if addflag then write(sim, ' ');
  m := 1;
  while (m <= length(a)) and (a[m] <> '.') do begin
    name[m] := a[m];
    m := m + 1
  end; {while}
  name[0] := chr(m - 1);
  fptr := findname(name);
  if fptr = nil then begin
    err := true;
    write('Error. Component <');
    swrt(output, name);
    writeln('> not found.');
```

```

while m <= length(a) do begin
    b[n] := a[m];
    n := n + 1;
    m := m + 1
end; {while}
b[0] := chr(n - 1);
tobit := str2num(b);
toflag := true;
end; {if}
if fromflag then
    write(sim, 'land(');
fptr := findname(name);
if fptr <> nil then
    if fptr^.kind = mem then
        if tempflag then begin
            write(sim, 'temp');
            swrt(sim, fptr^.name)
        end
    else
        begin
            write(sim, 'ljb');
            swrt(sim, name);
            write(sim, '[');
            expr(fptr^.addr, tempflag);
            write(sim, ']')
        end {if}
    else begin
        write(sim, 'ljb');
        swrt(sim, name)
    end; {if}
if fromflag then begin
    write(sim, ', ');
    bits := highbits[frombit];
    if toflag then begin
        for m := frombit + 1 to tobit do
            bits := bits + highbits[m];
    end; {if}
    write(sim, bits:1, ')');
end; {if}
if frombit > numbits then
    write(sim, ' div ', highbits[frombit - numbits]:1)
else
    if numbits - frombit <> 0 then
        write(sim, ' * ', highbits[numbits - frombit]:1);
if fromflag then
    if toflag then
        numbits := numbits + tobit - frombit + 1
    else
        numbits := numbits + 1
else

```

```

        numbits := 31;
        addflag := true
    end (case letters)
    else begin
        err := true;
        write('Error. Malformed expression ');
        swrt(output, str);
        writeln('.');
        printcomperr;
        goto l
    end; {case}
    if numbits > 31 then begin
        err := true;
        write('Error. Too many bits in ');
        swrt(output, str);
        writeln('.');
        goto l
    end; {if}
    j := i - 1;
    i := i - 1
until i < 0;
if dirtyflag then
    if consttotal <> 0 then
        write(sim, ' + ', consttotal:l)
    else
        else
            write(sim, consttotal:l)
end; {expr}

procedure genfunctions;
{*****}
(*
(* This procedure generates the variable declarations, memory *)
(* initialization procedure, alu function, input function, *)
(* and output procedure. *)
(*
{*****}

var vptr: valueptr;
begin
    {generate variable declarations}
    ptr := comptable;
    write(sim, 'var ');
    varflag := false;
    repeat
        if (varflag) then
            if (ptr^.kind in [alu, sel]) then begin
                write(sim, ', ljb');
                swrt(sim, ptr^.name)
            end

```

```

else begin
  write(sim, ', temp');
  swrt(sim, ptr^.name);
  write(sim, ', adr');
  swrt(sim, ptr^.name);
  write(sim, ', data');
  swrt(sim, ptr^.name);
  write(sim, ', opn');
  swrt(sim, ptr^.name);
end
else
  if (ptr^.kind in [alu, sel]) then begin
    varflag := true;
    write(sim, 'ljb');
    swrt(sim, ptr^.name);
  end
  else begin
    write(sim, 'temp');
    swrt(sim, ptr^.name);
    write(sim, ', adr');
    swrt(sim, ptr^.name);
    write(sim, ', data');
    swrt(sim, ptr^.name);
    write(sim, ', opn');
    swrt(sim, ptr^.name);
    varflag := true;
  end;
  ptr := ptr^.link
until ptr = nil;
writeln(sim, ': integer;');
writeln(sim, '    cycles, cyclecount: integer;');
ptr := comtable;
repeat
  if ptr^.kind = mem then begin
    write(sim, '    ljb');
    swrt(sim, ptr^.name);
    writeln(sim, ': array[0..', abs(ptr^.number) - 1:1, '] of
      integer;');
  end; (if)
  ptr := ptr^.link
until ptr = nil;

(generate bit and function)
writeln(sim);
writeln(sim, 'function land (a, b: integer): integer;');
writeln(sim, 'type bitnos = 0..31;');
writeln(sim, '    bigset = set of bitnos;');
writeln(sim, 'var intset: record case boolean of');
writeln(sim, '    false: (i, j: integer);');
writeln(sim, '    true: (x, y: bigset);');

```

```

writeln(sim, '          end;');
writeln(sim, 'begin');
writeln(sim, 'with intset do begin');
writeln(sim, '  i := a;');
writeln(sim, '  j := b;');
writeln(sim, '  x := x * y;');
writeln(sim, '  land := i;');
writeln(sim, '  end');
writeln(sim, 'end (land);');

(generate procedure to initialize memories)
writeln(sim);
writeln(sim, 'procedure initvalues;');
writeln(sim, 'var i: integer;');
writeln(sim, 'begin');
ptr := comptable;
while ptr <> nil do begin
  if ptr^.kind = mem then begin
    if ptr^.number < 0 then begin
      vptr := ptr^.values;
      for i := 0 to -ptr^.number - 1 do begin
        write(sim, '  ljb');
        swrt(sim, ptr^.name);
        writeln(sim, '[', i:l, '] := ', vptr^.value:l, ');');
        vptr := vptr^.link
      end; (for)
    end
  else begin
    writeln(sim, 'for i := 0 to ', ptr^.number - 1:l, ' do');
    write(sim, '  ljb');
    swrt(sim, ptr^.name);
    writeln(sim, '[i] := 0;');
    end; (if)
    write(sim, '  temp');
    swrt(sim, ptr^.name);
    writeln(sim, ' := 0;')
  end; (if)
  ptr := ptr^.link
end; (while)
writeln(sim, 'end; (initvalues)');

(generate function to calculate alu functions)
writeln(sim);
writeln(sim, 'function dologic(funcnt, left, right: integer):
integer;');
writeln(sim, 'const mask = ', highbits[30] - 1 + highbits[30]:l,
'');
writeln(sim, 'var value : integer;');
writeln(sim, 'begin');
writeln(sim, '  value := 0;');

```

```

writeln(sim, ' case funct of');
writeln(sim, '   0 : value := 0;');
writeln(sim, '   1 : value := right;');
writeln(sim, '   2 : value := left;');
writeln(sim, '   3 : value := mask - left;');
writeln(sim, '   4 : value := left + right;');
writeln(sim, '   5 : value := left - right;');
writeln(sim, '   6 : while (right > 0) and (left <> 0) do begin');
      left := land(left + left, mask);
      value := left;
      right := right - 1;
    end;
writeln(sim, '   7 : value := left * right;');
writeln(sim, '   8 : value := land(left, right);');
writeln(sim, '   9 : value := left + right - land(left, right);');
writeln(sim, '  10: value := left + right - land(left, right) *
      2;');
writeln(sim, '  11: value := 0;');
writeln(sim, '  12: if left = right then value := 1;');
writeln(sim, '  13: if left < right then value := 1;');
      end; (case);
writeln(sim, ' dologic := value;');
writeln(sim, 'end; (dologic);');

```

(generate function for input to memory)

```

writeln(sim);
writeln(sim, 'function sinput(address: integer): integer;');
writeln(sim, 'var datum: char;');
writeln(sim, '  data: integer;');
writeln(sim, 'begin');
  if address = 0 then begin;
    read(input, datum);
    sinput := ord(datum);
  end;
  else if address = 1 then begin;
    read(input, data);
    sinput := data;
  end;
  else begin;
    write(output, 'Input from address ', address:1,
      ' : ');
    readln(input, data);
    sinput := data;
  end;
writeln(sim, 'end; (sinput);');

```

(generate procedure for output from memory)

```

writeln(sim);
writeln(sim, 'procedure soutput(address, data: integer);');
writeln(sim, 'begin');

```

```

        writeln(sim, ' if address = 0 then writeln(output, chr(data))');
        writeln(sim, ' else if address = 1 then writeln(output, data)');
        writeln(sim, ' else writeln(output, 'Output to address ',
            address:1, ': ', data:1)');
        writeln(sim, 'end; (soutput)');
    end; (genfunctions)

procedure checkname (name: string);
{*****}
(*
(* This procedure checks all names for valid characters. If
(* the first character is not a letter, or the remaining
(* characters are not letters or numbers, then an error is
(* reported.
(*
(*
{*****}

var start, i: integer;
begin
    if name[1] = '-' then start := 2
    else start := 1;
    if not (name[start] in letters) then err := true;
    for i := start + 1 to length(name) do
        if not (name[i] in letters) and not (name[i] in numbers) then
            err := true;
    if err then begin
        write('Error. Component name ');
        swrt(output, name);
        writeln(' invalid, use letters and numbers only.');
```

'

```

        goto 1
    end; (if)
end; (checkname)

procedure gettoken;
{*****}
(*
(* This procedure gets each whitespace delimited string of
(* characters and returns them in the global variable token.
(* Macro substitution is done here as well. If a macro name
(* is found in the string, the actual text of the macro is
(* substituted immediately.
(*
(*
{*****}

var macro: string;
    ptr : macroptr;
begin
    token[0] := chr(0);
    if gettokenend then begin
        token[0] := chr(1);
```

```

token[1] := '.';
gettokenend := false
end
else begin
  while (ch in whitespace) and (not eof(inf)) do
    if ch = '(' then
      while ch <> ')' do
        read(inf, ch)
      end
    else
      read(inf, ch);
    end if end while
  while not (ch in whitespace) and (not eof(inf)) do begin
    {substitute macro name for actual macro text}
    if endmacrodef and (ch = '~') then begin
      macro[0] := chr(0);
      concat1(macro, ch);
      read(inf, ch);
      while not (ch in whitespace) and (not eof(inf)) and
        ((ch in letters) or (ch in numbers)) do begin
        concat1(macro, ch);
        read(inf, ch)
      end; (while)
      ptr := macrotable;
      while (ptr <> nil) and (not strcmp(macro, ptr^.name)) do
        ptr := ptr^.link;
      if ptr = nil then begin
        write('Error. Macro <');
        swrt(output, macro);
        writeln('> not defined.');
```

```

        err := true;
        goto 1
      end
    else
      concat(token, ptr^.macro)
    end
  else begin
    concat1(token, ch);
    read(inf, ch)
  end; (if)
end; (while)
end; (if)
if (token[ord(token[0])] = '.') and (ord(token[0]) <> 1) then begin
  token[0] := chr(ord(token[0]) - 1);
  gettokenend := true
end;
end; (gettoken)

```

```

procedure addname (namein: string; printflag: boolean);
(*****
*)
*) This procedure adds the component name and all of the data *)
*) associated with it to the data structure. *)
*)
*)
(*****)

var ptr: nameptr;
begin
  checkname(namein);
  if nametable = nil then begin
    new(nametable);
    with nametable^ do begin
      link := nil;
      name := namein;
      print := printflag;
      used := false
    end; {with}
  end
  else begin
    ptr := nametable;
    while ptr^.link <> nil do begin
      ptr := ptr^.link;
    end;
    new(ptr^.link);
    with ptr^.link^ do begin
      link := nil;
      name := namein;
      print := printflag;
      used := false
    end; {with}
  end; {if}
end; {addname}

procedure name;
(*****
*)
*) This procedure reads the component name from the input *)
*) file. *)
*)
*)
(*****)

begin
  while token[1] <> '.' do begin
    if token[length(token)] = '*' then begin
      token[0] := chr(ord(token[0])-1);
      addname(token, true)
    end
    else
  
```

```

        addname(token, false);
        gettoken;
    end; {while}
    gettoken;
end; {name}

procedure macrodef;
(*****)
(*
(* This procedure reads and stores the macro definition in
(* the macro data structure.
*)
*)
(*****)

var ptr: macroptr;
begin
    checkname(token);
    new(macrotable);
    with macrotable^ do begin
        link := nil;
        name := token;
        gettoken;
        macro := token
    end; {with}
    ptr := macrotable;
    gettoken;
    while token[1] = '~' do begin
        checkname(token);
        new(ptr^.link);
        ptr := ptr^.link;
        with ptr^ do begin
            link := nil;
            name := token;
            endmacrodef := true;
            gettoken;
            endmacrodef := false;
            macro := token
        end; {with}
        gettoken
    end; {while}
end; {macrodef}

procedure cycle;
(*****)
(*
(* This procedure gets the number of cycles which are to
(* be simulated.
*)
*)
(*****)

```

```

begin
  gettoken;
  numcycles := str2num(token);
  gettoken
end; {cycle}

procedure readit;
(*****)
(*                                           *)
(* This procedure reads the input file, calling any necessary *)
(* support procedures. It places the specification in the *)
(* data structure for processing by other procedures. *)
(*                                           *)
(*****)

var nptr: nameptr;
    flag: boolean;
    vptr, ovptr: valueptr;
    cptr, ocptr: caseptr;
begin
  endmacrodef := false;
  comment[0] := chr(0);
  repeat
    read(inf, ch);
    concat1(comment, ch)
  until eoln(inf);
  writeln(sim, 'program simulator(input, output);');
  if comment[1] <> '#' then begin
    err:= true;
    writeln('Error. Comment required.');
```

C21

```

end
else begin
  while ptr^.link <> nil do
    ptr := ptr^.link;
    new(ptr^.link);
    ptr := ptr^.link
  end; {if}
  with ptr^ do begin
    link := nil;
    used := false;
    i := 0;
    numcomponents := numcomponents + 1;
    case token[l] of
      'A' : kind := alu;
      'S' : kind := sel;
      'M' : kind := mem
    end; {case}
    case kind of
      alu : begin
        gettoken;
        name := token;
        gettoken;
        funct := token;
        gettoken;
        left := token;
        gettoken;
        right := token;
        gettoken;
      end;
      sel : begin
        gettoken;
        name := token;
        gettoken;
        select := token;
        i := 0;
        gettoken;
        repeat
          new(cptr);
          cptr^.casevalue := token;
          cptr^.link := nil;
          if i = 0 then
            ptr^.cases := cptr
          else
            ocptr^.link := cptr;
            ocptr := cptr;
            i := i + 1;
            gettoken
          until (token[l] in ['A', 'S', 'M', '.']) and
              (length(token) = 1);
        until (token[l] in ['A', 'S', 'M', '.']) and
              (length(token) = 1);
      end;
    end;
  end;
end;

```

```

mem : begin
  gettoken;
  name := token;
  gettoken;
  addr := token;
  gettoken;
  data := token;
  gettoken;
  opn := token;
  gettoken;
  if token[1] = '-' then begin
    for i := 2 to length(token) do
      token[i-1] := token[i];
    token[0] := chr(ord(token[0]) - 1);
    number := -(str2num(token));
    for i := 0 to abs(number) - 1 do begin
      gettoken;
      new(vptr);
      if i = 0 then
        values := vptr
      else
        ovptr^.link := vptr;
        ovptr := vptr;
        vptr^.value := str2num(token);
        vptr^.link := nil
      end; {for}
    end
  else
    number := str2num(token);
    gettoken;
  end;
end; {case}
nptr := nametable;
repeat
  flag := strcmp(nptr^.name, name);
  if flag then begin
    used := true;
    nptr^.used := true
  end
  else
    nptr := nptr^.link;
  until flag or (nptr = nil);
end; {with}
end
else begin
  err:= true;
  write('Error. Component expected. Got <');
  swrt(output, token);
  writeln('> instead. ');
  printcomperr;

```

```

        goto l
    end;
end; (while);
writeln(numcomponents:1, ' components read.');
```

```

end; (readit)

procedure checkdcl;
(*****)
(*
(* This procedure checks the declarations of the components. *)
(* if a component is declared but not used, or used, but not *)
(* declared, a warning message is issued. Code generation *)
(* continues. *)
(*
(*****)

var nptr: nameptr;
    cptr: compptr;
begin
    nptr := nametable;
    repeat
        with nptr^ do begin
            if not used then begin
                write('Warning: ');
                swrt(output, name);
                writeln(' declared but not defined.')
```

```

            end; (if)
            nptr := nptr^.link
        end; (with)
    until nptr = nil;
    cptr := comtable;
    repeat
        with cptr^ do begin
            if not used then begin
                write('Warning: ');
                swrt(output, name);
                writeln(' defined but not declared.')
```

```

            end; (if)
            cptr := cptr^.link
        end; (with)
    until cptr = nil
end;
```

```

function compare (a, b: string): boolean;
(*****)
(*                                     *)
(* This function breaks the expression in b into the      *)
(* individual pieces, and compares these pieces with the  *)
(* string a. If the any part of b is in a, then compare  *)
(* returns true.                                          *)
(*                                     *)
(*****)

var i, j: integer;
    c: string;
begin
    i := 1;
    compare := false;
    while i <= length(b) do begin
        j := 1;
        if b[i] in letters then begin
            while ((b[i] in letters) or (b[i] in numbers)) and
                (i <= length(b)) do begin
                c[j] := b[i];
                j := j + 1;
                i := i + 1
            end; {while}
            c[0] := chr(j - 1);
            if strcmp(a, c) then
                compare := true;
        end; {if}
        i := i + 1;
    end; {while}
end; {compare}

function dependent (a, b: compptr): boolean;
(*****)
(*                                     *)
(* This function returns true if the component a depends on *)
(* the value of component b.                                     *)
(*                                     *)
(*****)

var c: string;
    cptr: caseptr;
begin
    dependent := false;
    c:= b^.name;
    with a^ do
        case kind of
            alu: if compare(c, funct) or compare(c, left) or
                compare(c, right) then
                dependent := true;

```

```

sel: begin
    if compare(c, select) then dependent := true;
    cptr := cases;
    while cptr <> nil do begin
        if compare(c, cptr^.casevalue) then
            dependent := true;
        cptr := cptr^.link
    end; {while}
end; {case sel}
mem: dependent := false;
end; {case}
end; {dependent}

procedure orderit;
(******)
(* This procedure sorts the alu and selector components in *)
(* dependency order. It also checks for circular *)
(* dependencies. *)
(* *****)

var i, j, k, num: integer;
    templ, ptr: compptr;
    a, b: array[1..maxcomponents] of compptr;
begin
    i := 1;
    j := 1;
    num := 0;
    ptr := comptable;
    {break component list into 2 pieces: one with alus and
    selectors, and the other with memories}
    a[1] := nil;
    a[2] := nil;
    while ptr <> nil do begin
        case ptr^.kind of
            alu, sel: begin
                a[i] := ptr;
                i := i + 1;
            end;
            mem: begin
                b[j] := ptr;
                j := j + 1;
            end
        end; {case}
        ptr := ptr^.link
    end; {while}
    a[i] := nil;
    b[j] := nil;
    num := i - 1;

```

```

(sort alus and selectors)
for k := 1 to num do
  for i := 1 to num do
    for j := i to num do
      if dependent(a[i], a[j]) then begin
        templ := a[j];
        a[j] := a[i];
        a[i] := templ
      end; {if}
    (check for remaining dependencies)
  for i := 1 to num do
    for j := i to num do
      if dependent(a[i], a[j]) then begin
        err := true;
        write('Error. Circular dependency with ');
        swrt(output, a[j]^name);
        write(' and/or ');
        swrt(output, a[i]^name);
        writeln('.');
        goto 1
      end; {if}
    j := 1;
    if a[i] <> nil then
      comptable := a[i]
    else begin
      j := 2;
      comptable := b[i]
    end; {if}
    ptr := comptable;
    i := 2;
    while a[i] <> nil do begin
      ptr^.link := a[i];
      ptr := a[i];
      i := i + 1
    end; {while}
    while b[j] <> nil do begin
      ptr^.link := b[j];
      ptr := b[j];
      j := j + 1
    end; {while}
    ptr^.link := nil
  end; {orderit}

procedure init;
{*****}
(*
(* This procedure initializes variables.
(*
(*
{*****}

```

```

begin
  donereading := false;
  nametable := nil;
  comptable := nil;
  macrotable := nil;
  numcomponents := 0;
  gettokenend := false;
  varflag := false;
  numbers := ['0'..'9'];
  letters := ['a'..'z', 'A'..'Z'];
  hexnums := ['0'..'9', 'A'..'F'];
  whitespace := [chr(9), chr(10), chr(13), ' ', '(', ')'];
  rewrite(sim, 'simulator.p');
  if argc = 2 then
    argv(1, filename)
  else begin
    writeln('Enter name of input file. ');
    i := 0;
    repeat
      read(filename[i]);
      i := i + 1
    until eoln
    end;
    reset(inf, filename);
    write('Reading file ');
    for i := 0 to 20 do
      write(filename[i]);
    writeln;
    highbits[0] := 1;
    for i := 1 to 31 do
      highbits[i] := highbits[i-1] * 2;
    end; {init}

  procedure gencode;
  (*****
  (*
  (* This procedure generates the Pascal code for the main
  (* program of the simulator.
  (*
  (*
  (*****
  var fptr: compptr;
      flag, flag2: boolean;
      cptr: caseptr;
      mask: integer;
  begin
    mask := highbits[30] - 1 + highbits[30];
    {generate main program}
    writeln(sim);
    writeln(sim, 'begin');

```

```

writeln(sim, 'initvalues;');
write(sim, 'cycles := ');
writeln(sim, numcycles:1, ');');
writeln(sim, 'if cycles = 0 then begin');
writeln(sim, '  writeln('Number of cycles to trace');');
writeln(sim, '  read(cycles);');
writeln(sim, 'end;');
writeln(sim, 'cyclecount := 0;');

{start of main loop}
writeln(sim, 'while cyclecount <= cycles do begin');

{generate assignments to components}
ptr := comtable;
while ptr <> nil do begin
  case ptr^.kind of
    alu: begin
      with ptr^ do begin
        if numeric(func) then
          case str2num(func) of
            0: begin
              write(sim, 'ljb');
              swrt(sim, name);
              writeln(sim, ' := 0;');
            end;
            1: begin
              write(sim, 'ljb');
              swrt(sim, name);
              write(sim, ' := ');
              expr(right, true);
              writeln(sim, ';')
            end;
            2: begin
              write(sim, 'ljb');
              swrt(sim, name);
              write(sim, ' := ');
              expr(left, true);
              writeln(sim, ';')
            end;
            3: begin
              write(sim, 'ljb');
              swrt(sim, name);
              write(sim, ' := ', mask:1, ' - ');
              expr(left, true);
              writeln(sim, ';')
            end;
            4: begin
              write(sim, 'ljb');
              swrt(sim, name);
              write(sim, ' := ');

```

```

    expr(left, true);
    write(sim, ' + ');
    expr(right, true);
    writeln(sim, ';');
end;
5: begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := ');
    expr(left, true);
    write(sim, ' - ');
    expr(right, true);
    writeln(sim, ';');
end;
6: begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := dologic(6, ');
    expr(left, true);
    write(sim, ', ');
    expr(right, true);
    writeln(sim, ');');
end;
7: begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := ');
    expr(left, true);
    write(sim, ' * ');
    expr(right, true);
    writeln(sim, ';');
end;
8: begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := ');
    write(sim, 'land(');
    expr(left, true);
    write(sim, ', ');
    expr(right, true);
    writeln(sim, ');');
end;
9: begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := ');
    expr(left, true);
    write(sim, ' + ');
    expr(right, true);
    write(sim, ' - land(');

```

```

        expr(left, true);
        write(sim, ', ');
        expr(right, true);
        writeln(sim, ');')
    end;
10:begin
    write(sim, 'ljb');
    swrt(sim, name);
    write(sim, ' := ');
    expr(left, true);
    write(sim, ' + ');
    expr(right, true);
    write(sim, ' - land(');
    expr(left, true);
    write(sim, ', ');
    expr(right, true);
    writeln(sim, ');')
end;
11:begin
    write(sim, 'ljb');
    swrt(sim, name);
    writeln(sim, ' := 0;')
end;
12:begin
    write(sim, 'if ');
    expr(left, true);
    write(sim, ' = ');
    expr(right, true);
    write(sim, ' then ljb');
    swrt(sim, name);
    writeln(sim, ' := 1');
    write(sim, ' else ljb');
    swrt(sim, name);
    writeln(sim, ' := 0;')
end;
13:begin
    write(sim, 'if ');
    expr(left, true);
    write(sim, ' < ');
    expr(right, true);
    write(sim, ' then ljb');
    swrt(sim, name);
    writeln(sim, ' := 1');
    write(sim, ' else ljb');
    swrt(sim, name);
    writeln(sim, ' := 0;')
end
end {case optimize alu functions}
else begin
    write(sim, 'ljb');

```

```

        swrt(sim, name);
        write(sim, ' := dologic(');
        expr(funct, true);
        write(sim, ', ');
        expr(left, true);
        write(sim, ', ');
        expr(right, true);
        writeln(sim, ');');
    end; {if}
end; {with}
end; {case alu}
sel: begin
    write(sim, 'case ');
    expr(ptr^.select, true);
    writeln(sim, ' of');
    i := 0;
    cptr := ptr^.cases;
    while cptr <> nil do begin
        write(sim, ' ', i:1, ' : ljb');
        swrt(sim, ptr^.name);
        write(sim, ' := ');
        expr(cptr^.casevalue, true);
        writeln(sim, ');');
        cptr := cptr^.link;
        i := i + 1
    end; {while}
    writeln(sim, 'end;');
end; {case sel}

mem: ;
end; {case}
ptr := ptr^.link
end; {while}

{generate trace statements}
nptr := nametable;
writeln(sim, 'write(''Cycle ', cyclecount:3);');
while nptr <> nil do begin
    if nptr^.print then begin
        write(sim, 'write('' ');
        swrt(sim, nptr^.name);
        write(sim, '= ', ');
        fptr := findname(nptr^.name);
        if fptr <> nil then
            if fptr^.kind = mem then begin
                write(sim, 'temp');
                swrt(sim, nptr^.name)
            end
        else begin
            write(sim, 'ljb');
            swrt(sim, nptr^.name)
        end
    end
end;

```

```

        end; (if)
        writeln(sim, ':l);')
    end; (if)
    nptr := nptr^.link
end; (while)
writeln(sim, 'writeln;');

(assign temporary memory values (adr, data, opn))
ptr := comtable;
while ptr <> nil do begin
    if ptr^.kind = mem then begin
        write(sim, 'adr');
        swrt(sim, ptr^.name);
        write(sim, ' := ');
        expr(ptr^.addr, true);
        writeln(sim, '');
        write(sim, 'data');
        swrt(sim, ptr^.name);
        write(sim, ' := temp');
        swrt(sim, ptr^.name);
        writeln(sim, '');
        write(sim, 'opn');
        swrt(sim, ptr^.name);
        write(sim, ' := ');
        expr(ptr^.opn, true);
        writeln(sim, '');
    end; (if)
    ptr := ptr^.link;
end; (while)

(assign memories their new values)
ptr := comtable;
while ptr <> nil do begin
    if ptr^.kind = mem then begin
        if numeric(ptr^.opn) then begin
            case land(str2num(ptr^.opn), 3) of
                0 : begin
                    write(sim, 'temp');
                    swrt(sim, ptr^.name);
                    write(sim, ' := ljb');
                    swrt(sim, ptr^.name);
                    write(sim, '[adr');
                    swrt(sim, ptr^.name);
                    writeln(sim, '];');
                end;
                1 : begin
                    write(sim, 'temp');
                    swrt(sim, ptr^.name);
                    write(sim, ' := ');
                    expr(ptr^.data, true);

```

```

        writeln(sim, ');');
        write(sim, 'ljb');
        swrt(sim, ptr^.name);
        write(sim, '[adr');
        swrt(sim, ptr^.name);
        write(sim, '] := temp');
        swrt(sim, ptr^.name);
        writeln(sim, ');')
    end;
2 : begin
    write(sim, 'temp');
    swrt(sim, ptr^.name);
    write(sim, ' := sinut(');
    expr(ptr^.data, true);
    writeln(sim, ');')
end;
3 : begin
    write(sim, 'temp');
    swrt(sim, ptr^.name);
    write(sim, ' := ');
    expr(ptr^.data, true);
    writeln(sim, ');');
    write(sim, 'soutut(');
    expr(ptr^.data, true);
    write(sim, ', temp');
    swrt(sim, ptr^.name);
    writeln(sim, ');')
end
end (case)
end
else begin
    write(sim, 'case land(opn');
    swrt(sim, ptr^.name);
    writeln(sim, ', 3) of');
    write(sim, ' 0: temp');
    swrt(sim, ptr^.name);
    write(sim, ' := ljb');
    swrt(sim, ptr^.name);
    write(sim, '[adr');
    swrt(sim, ptr^.name);
    writeln(sim, '];');
    writeln(sim, ' 1: begin');
    write(sim, '      temp');
    swrt(sim, ptr^.name);
    write(sim, ' := ');
    expr(ptr^.data, true);
    writeln(sim, ');');
    write(sim, '      ljb');
    swrt(sim, ptr^.name);
    write(sim, '[adr');

```

```

swrt(sim, ptr^.name);
write(sim, ' ] := temp');
swrt(sim, ptr^.name);
writeln(sim, ' ');
writeln(sim, '      end');
write(sim, ' 2: temp');
swrt(sim, ptr^.name);
write(sim, ' := sinput(adr');
swrt(sim, ptr^.name);
writeln(sim, ' ');
writeln(sim, ' 3: begin');
write(sim, '      temp');
swrt(sim, ptr^.name);
write(sim, ' := ');
expr(ptr^.data, true);
writeln(sim, ' ');
write(sim, '      soutput(adr');
swrt(sim, ptr^.name);
write(sim, ' , temp');
swrt(sim, ptr^.name);
writeln(sim, ' ');
writeln(sim, '      end');
writeln(sim, 'end; (case)')
end;

(generate code to trace writes)
flag := false;
flag2 := false;
if not (numeric(ptr^.opn)) and
    (numberofbits(ptr^.opn) >= 3) then
    flag := true
else
    if numeric(ptr^.opn) then
        if land(str2num(ptr^.opn), 4) = 4 then
            flag2 := true;
if flag then begin
    write(sim, 'if land(');
    expr(ptr^.opn, true);
    writeln(sim, ', 5) = 5 then');
    write(sim, ' ')
end;
if flag or flag2 then begin
    write(sim, 'writeln(' Write to ');
    swrt(sim, ptr^.name);
    write(sim, ' at ', ');
    expr(ptr^.addr, true);
    write(sim, ':1, ' : ', ');
    expr(ptr^.name, true);
    writeln(sim, ':1);')
end; {if}

```

```

(generate code to trace reads)
flag := false;
flag2 := false;
if not (numeric(ptr^.opn)) and (numberofbits(ptr^.opn) >=4) then
    flag := true
else
    if numeric(ptr^.opn) then
        if land(str2num(ptr^.opn), 8) = 8 then
            flag2 := true;
    if flag then begin
        write(sim, 'if land(');
        expr(ptr^.opn, true);
        writeln(sim, ', 9) = 8 then');
        write(sim, ' ')
    end;
    if flag or flag2 then begin
        write(sim, 'writeln('' Read from ');
        swrt(sim, ptr^.name);
        write(sim, ' at ', ');
        expr(ptr^.addr, true);
        write(sim, ':1, '' : ', ');
        expr(ptr^.name, true);
        writeln(sim, ':1);')
    end; (if)

end; (if)
ptr := ptr^.link
end; {while}

(generate code to check for end of loop)
writeln(sim, 'cyclecount := cyclecount + 1;');
writeln(sim, 'if cyclecount = cycles + 1 then begin');
writeln(sim, '    writeln(''Continue to cycle (0 to quit)'');');
writeln(sim, '    read(cycles);');
writeln(sim, 'end;');
writeln(sim, 'end; {while}');
{end of main loop}

writeln(sim, 'end.');
```

```

end; (gencode)

begin (main)
    init;
    readit;
    donereading := true;
    writeln('Sorting components.');
```

```

    orderit;
    checkdcl;
    writeln('Generating code.');
```

```
    genfunctions;  
    gencode;  
1:  
    if err then  
        writeln('Error in program (no code generated).');  
    end.
```

Appendix D

Example Stack Machine Simulator Specification

Itty Bitty Stack Machine Simulator Specification

```
{Macro bit functions}
~pack #000000000000 (=zero.0.~k)
~k 11      {high bit position in LDC loop}
~m 11      {high bit of RAM address}
~n 12      {I/O select bit in RAM address}
~d 5       {~d selects right operand for alu}
           {~d selects fp to ALU right}
~dd 7      {~d..~dd selects write data}
~st 4      {0..~st selects next state}
~a 10      {~a signals absolute addressing}
~f 11      {~f signals frame pointer update}
~g 9       {~g signals goto, not increment}
~i 6       {~i signals increment or branch}
~l 3       {~l loads left from ram}
~o 1       {~o signals pop, not push; ~z adds, not loads}
~p 7       {~p signals stack pointer update}
~r 4       {~r loads right from ram}
~s 12      {~s selects state from opcode+n}
~v 0       {~v selects frame pointer to load, not 1 to add}
~w 8       {~w writes into stack ram}
           {~w selects LDC loop test, not BZ}
~x 13      {~x enables condition test}
~y 5       {~y selects frame offset for ram address}
~z 2       {~z indicates escape; current opcode}

{Component list ...}
state rom parm relpc offset psp sp pushpop selfp fp afp addr
ram op left right neg selr alu exit write newpc pc prog ir
data newst.

{Component specifications...}
M state 0 newst 1 1      {write next state (at end)}

A exit %110,rom.~w ram rom.~w,~pack

S newst rom.~s.~x,exit.0  {~s selects state from opcode+n}
  {000} parm.0.~st        {next state from rom}
```

{001} parm.0.~st	
{010} 1,rom.~z,prog.0.3	{~z indicates escape; current opcode}
{011} 1,rom.~z,prog.0.3	
{100} 0	{~x enables condition test}
{101} parm.0.~st	{~w selects LDC loop test, not BZ}
{110} 0	
{111} 1,rom.~z,prog.0.3	
M pc 0 newpc rom.~i 1	{~i signals increment or branch}
A newpc %100 relpc offset	
S relpc rom.~a pc 0	{~a signals absolute addressing}
S offset rom.~g 1 left	{~g signals goto, not increment}
M sp 0 pushpop rom.~p 1	{~p signals stack pointer update}
A pushpop rom.~z,#0,rom.~o sp psp	
S psp rom.~v.~z	{~v selects frame pointer to load, not 1 to add}
{0-2} 0 0 0	{~o signals pop, not push; ~z adds, not loads}
{011} fp	
{100} 1	
{101} left	
{110} 1	
{111} right	
M fp 0 selfp rom.~f 1	{~f signals frame pointer update}
S selfp ir.0 sp ram	{load from current sp or from stack}
S addr rom.~y sp afp	{~y selects frame offset for ram address}
A afp %100 fp left	{frame offset = fp+left}
M left 0 ram rom.~l 1	{~l loads left from ram}
M right 0 ram rom.~r 1	{~r loads right from ram}
A neg %101 0 ram	{negative of right}
S selr parm.~d	{~d selects right operand for alu}

```

(0) right
(1) fp

A alu op ram selr

M ir 0 prog rom.~s 1 {So that prog isn't held up, hack
                      remembers the value of prog at fetch
                      time. Note that prog must be used to
                      calculate newst because ir won't be
                      valid until the cycle following the
                      fetch}

M data 0 prog parm.8 1      { gets prog's value when it is
                             data }

S write parm.~d.~dd        {~d.~dd selects write data}
{000} alu
{001} alu                    {~d selects fp to ALU right}
{010} fp
{011} pc
{100} ir.0
{101} ram.0.~k,data.0.3
{110} left
{111} neg

M ram addr.0.~m write addr.~n,rom.~w 4096 {~w writes into
                                             stack ram the 11 sets trace reads & writes }

S op ir.0.3                {Opcode-ALU function ROM follows}
{0} 0 {1} 0 {2} %1 {3} %100 {4} %1 {5} %1000 {6} %1101
{7} %1100 {8} %11 {9} 0 {10} %100 {11} %111 {12} %10
{13} %1 {14} %1100 {15} %101

S rom state.0.5            {decode rom follows}
{00 fetch}    ^~s+^~l+^~r+^~i
{01 LDZ}      ^~w
{02 LD0}      ^~w {~dd=4} ^~w {~dd=5}
{04 ST...}    ^~w+^~y {goto $19 so addr and ram can bounce
                  back}
{05 =NOT}     ^~w
{06 =NEG}     ^~w {~dd=7}
{07 EQUAL}    ^~w {goto NEG}
{08 INDEX...} ^~y+^~w+^~l {goto SWAP+2}
{09 SWAP...}  ^~w {~dd=6}
{0A EXIT...}  ^~z+^~p+^~o+^~v+^~l ^~a+^~g
{0C LD}       ^~w
{0D ST}       ^~r+^~z+^~p+^~o
{0E BZ}       ^~x+^~z+^~p+^~o ^~i+^~g
{10 LDC}      ^~w {parm=^5+^7+^8, ~dd=5}
{11 LDC}      ^~w {parm=^5+^7+^8}
{12 SWAP}     ^~l+^~z+^~p+^~w
{13 INDEX}    ^~r

```

```

(14 LDC)      ^~w+^~i {parm=^5+^7+^8}
(15 EXIT)     ^~f+^~p+^~o+^~z
(16 CALL)     ^~w+^~a+^~g {-dd=3}
(17 LDC)      ^~w+^~i {parm=^5+^7+^8, ~dd=5}
(18 LDC)      ^~w+^~i {parm=^7+^8, ~dd=4}
(19-1E)       0 0 0 0 0 0 {19-1E are interim states (see
                                parm)}
(1F esc)      ^~s+^~z+^~i
(20 esc)      0
(21 LDZ)      ^~z+^~p
(22 LD0)      ^~z+^~p+^~i
(23 LD1)      ^~z+^~p+^~i {goto LD0+1}
(24 DUPE)     ^~z+^~p {goto LD+1}
(25 AND)      ^~z+^~p+^~o {goto NOT, goto 1E}
(26 LESS)     ^~z+^~p+^~o {goto EQUAL+1, goto 1D}
(27 EQUAL)    ^~z+^~p+^~o {goto 1D}
(28 NOT)      ^~w
(29 NEG)      ^~w {-dd=7}
(2A ADD)      ^~z+^~p+^~o {goto NOT, goto 1E}
(2B MPY)      ^~z+^~p+^~o {goto NOT, goto 1E}
(2C LD)       ^~y
(2D ST)       ^~z+^~p+^~o {goto 1C}
(2E BZ)       ^~z+^~p+^~o {goto 1B}
(2F GLOB)     ^~w {-dd=1}
(30 NOP)      0
(31 LDC)      ^~z+^~p+^~i
(32 SWAP)     ^~z+^~p+^~o {goto 1A}
(33 INDEX)    ^~z+^~p+^~o
(34 ENTER)    ^~w+^~f+^~p+^~z+^~v {-dd=2}
{ enter does the following: write fp to ^sp, fp gets sp,
  sp gets sp + left, increment pc }
(35 EXIT)     ^~p+^~o+^~v
(36 CALL)     ^~i
(37-3F) 0 0 0 0 0 0 0 0 0

```

```

S parm state.0.5      {part 2 of decode rom}
{00} 0 0 128+3+^8 160 25 0 224 6 9 192 11 0 0 4 15 25
{10} 0+^5+^7+^8 16+^5+^7+^8 9 8 17+^5+^7+^8 10 96
      20+^5+^7+^8
{18} 23+^7+^8 0 18 14 13 7 5 0
{20} 31 1 2 2 12 30 29 29 0 224 30 30 12 28 27 32
{30} 0 24 26 19 64 21 22 0 0 0 0 0 0 0 0 0

```

```

M prog pc 0 0 -133 {-1024}      {program rom follows}
0 0 3 10      { 000: 1d1 10 ; ldc 26 }
0 4      { enter }
      { ; count = 0 }
1      { ldz }
2 4      { ld0 4 }
13      { st }
      { ; for(i=0; i<=size; i++)
        ; flags[i] = true }

```

```

2 5      ( ld0 5 ; one less than array addr
          since 1 is added immediately )
2 1      ( FOR1 ld0 1 )
10      ( add )
4        ( dupe )
2 1      ( ld0 1 )
0 2      ( swap )
13       ( st )
4        ( dupe )
3 10     ( ldl 10 ; ldc 26 = size + array
          offset )
7        ( equal )
3 1      ( ldl 1; ldc 17 = endfor1 - for1 )
9        ( neg )
14       ( bz )
2 5      ( ENDFOR1 ld0 5 ; loc 5 unused, get
          junk off stack )
13       ( st )
          ( ; for (i=0; i <= size; i++) )
1        ( ldz )
2 1      ( ld0 1 )
13       ( st )
          ( ; if (flags[i]) )
2 1      ( FOR2 ld0 1 ; get i )
12       ( ld )
2 6      ( ld0 6 ; get start of flags )
10       ( add )
12       ( ld ; get flags[i] )
0 1 0 0 3 10 ( ldc 58=$3a ; INC - IF )
14       ( bz )
          ( ; prime = i + i + 3 )
2 1      ( IF ld0 1 ; get i )
12       ( ld )
4        ( dupe )
4        ( dupe )
10       ( add ; i + i )
2 3      ( ld0 3 )
10       ( add ; this is the prime number )
4        ( dupe )
0 1 1 0 0 0 ( ld0 4096; output prime )
13       ( st )
4        ( dupe )
2 2      ( ld0 2 ; store prime )
13       ( st )
          ( ; for(k=i+prime; k <= size;
          k+=prime) ; flags[k] = false )
10       ( add ; k=i+prime )
4        ( FOR3 dupe )
2 6      ( ld0 6 )
10       ( add ; add array address )
1        ( ldz )
0 2      ( swap )

```

13		{ st ; flags[k]=0 }
2	2	{ ld0 2; get prime }
12		{ ld }
10		{ add ; k = k + prime }
4		{ dupe }
3	5	{ ld1 5 ; ldc 21 = size + 1 }
6		{ less }
2	5	{ ld0 ; ENDFOR3 - SKIP }
14		{ bz }
1		{ SKIP ldz }
3	8	{ ld1 8 ; ldc 24=ENDFOR3-FOR3 }
9		{ neg }
14		{ bz ; forced jump }
2	5	{ ENDFOR3 ld0 5 ; here if
		not(k<size+1) }
13		{ st ; store it to get it off the
		stack }
		{ ;count++ }
2	4	{ ld0 4 }
12		{ ld }
2	1	{ ld0 1 }
10		{ add }
2	4	{ ld0 4 }
13		{ st }
		{ ; i++ }
2	1	{ INC ld0 1 }
12		{ ld }
2	1	{ ld0 1 }
10		{ add }
4		{ dupe }
2	1	{ ld0 1 }
13		{ st }
3	5	{ ld1 5; ldc 21=size+1 }
7		{ equal }
0	1 0 0 5 13	{ ldc 93=\$5d ;ENDFOR2 - FOR2 }
9		{ neg }
14		{ bz; goto beginning of for loop }
0 0		{ ENDFOR2 nop }
0 0		
.		

Appendix E

Pascal Code for Example Specification

```
program simulator(input, output);
{# Itty Bitty Stack Machine Simulator Specification}
var ljbrom, ljbexit, ljbrelpc, ljboffset, ljbnewpc, ljbpsp,
    ljbpushpop, ljbselfp, ljbafp, ljbaddr, ljbneg, ljbparm,
    ljbop, ljbseir, ljbalu, ljbnewst, ljbwrite, tempstate,
    adrstate, datastate, opnstate, temppc, adrpc, datapc,
    opnpc, tempsp, adrsp, datasp, opnsp, tempfp, adrfp,
    datafp, opnfp, templeft, adrleft, dataleft, opnleft,
    tempright, adrright, dataright, opnright, tempir, adrir,
    datair, opnir, tempdata, adrdata, datadata, opndata,
    tempram, adrram, dataram, opnram, temprprog, adrprog,
    dataprog, opnprog: integer;
cycles, cyclecount: integer;
ljbstate: array[0..0] of integer;
ljbpc: array[0..0] of integer;
ljbop: array[0..0] of integer;
ljbfp: array[0..0] of integer;
ljbleft: array[0..0] of integer;
ljbright: array[0..0] of integer;
ljbir: array[0..0] of integer;
ljbdata: array[0..0] of integer;
ljbram: array[0..4095] of integer;
ljbprog: array[0..132] of integer;

function land (a, b: integer): integer;
type bitnos = 0..31;
    bigset = set of bitnos;
var intset: record case boolean of
    false: (i, j: integer);
    true: (x, y: bigset)
end;
begin
with intset do begin
    i := a;
    j := b;
    x := x * y;
    land := i
end
end {land};
```

```

procedure initvalues;
var i: integer;
begin
  for i := 0 to 0 do
    ljbstate[i] := 0;
    tempstate := 0;
  for i := 0 to 0 do
    ljbpc[i] := 0;
    temppe := 0;
  for i := 0 to 0 do
    ljbsp[i] := 0;
    tempse := 0;
  for i := 0 to 0 do
    ljbfp[i] := 0;
    tempfe := 0;
  for i := 0 to 0 do
    ljbleft[i] := 0;
    templeft := 0;
  for i := 0 to 0 do
    ljbright[i] := 0;
    tempright := 0;
  for i := 0 to 0 do
    ljbir[i] := 0;
    tempir := 0;
  for i := 0 to 0 do
    ljbdata[i] := 0;
    tempdata := 0;
  for i := 0 to 4095 do
    ljbram[i] := 0;
    tempram := 0;
    ljbprog[0] := 0;
    ljbprog[1] := 0;
    ljbprog[2] := 3;
    ljbprog[3] := 10;
    ljbprog[4] := 0;
    ljbprog[5] := 4;
    ljbprog[6] := 1;
    ljbprog[7] := 2;
    ljbprog[8] := 4;
    ljbprog[9] := 13;
    ljbprog[10] := 2;
    ljbprog[11] := 5;
    ljbprog[12] := 2;
    ljbprog[13] := 1;
    ljbprog[14] := 10;
    ljbprog[15] := 4;
    ljbprog[16] := 2;
    ljbprog[17] := 1;
    ljbprog[18] := 0;
    ljbprog[19] := 2;
    ljbprog[20] := 13;

```

```

ljbprog[21] := 4;
ljbprog[22] := 3;
ljbprog[23] := 10;
ljbprog[24] := 7;
ljbprog[25] := 3;
ljbprog[26] := 1;
ljbprog[27] := 9;
ljbprog[28] := 14;
ljbprog[29] := 2;
ljbprog[30] := 5;
ljbprog[31] := 13;
ljbprog[32] := 1;
ljbprog[33] := 2;
ljbprog[34] := 1;
ljbprog[35] := 13;
ljbprog[36] := 2;
ljbprog[37] := 1;
ljbprog[38] := 12;
ljbprog[39] := 2;
ljbprog[40] := 6;
ljbprog[41] := 10;
ljbprog[42] := 12;
ljbprog[43] := 0;
ljbprog[44] := 1;
ljbprog[45] := 0;
ljbprog[46] := 0;
ljbprog[47] := 3;
ljbprog[48] := 10;
ljbprog[49] := 14;
ljbprog[50] := 2;
ljbprog[51] := 1;
ljbprog[52] := 12;
ljbprog[53] := 4;
ljbprog[54] := 4;
ljbprog[55] := 10;
ljbprog[56] := 2;
ljbprog[57] := 3;
ljbprog[58] := 10;
ljbprog[59] := 4;
ljbprog[60] := 0;
ljbprog[61] := 1;
ljbprog[62] := 1;
ljbprog[63] := 0;
ljbprog[64] := 0;
ljbprog[65] := 0;
ljbprog[66] := 13;
ljbprog[67] := 4;
ljbprog[68] := 2;
ljbprog[69] := 2;
ljbprog[70] := 13;
ljbprog[71] := 10;
ljbprog[72] := 4;

```

```
ljbprog[73] := 2;  
ljbprog[74] := 6;  
ljbprog[75] := 10;  
ljbprog[76] := 1;  
ljbprog[77] := 0;  
ljbprog[78] := 2;  
ljbprog[79] := 13;  
ljbprog[80] := 2;  
ljbprog[81] := 2;  
ljbprog[82] := 12;  
ljbprog[83] := 10;  
ljbprog[84] := 4;  
ljbprog[85] := 3;  
ljbprog[86] := 5;  
ljbprog[87] := 6;  
ljbprog[88] := 2;  
ljbprog[89] := 5;  
ljbprog[90] := 14;  
ljbprog[91] := 1;  
ljbprog[92] := 3;  
ljbprog[93] := 8;  
ljbprog[94] := 9;  
ljbprog[95] := 14;  
ljbprog[96] := 2;  
ljbprog[97] := 5;  
ljbprog[98] := 13;  
ljbprog[99] := 2;  
ljbprog[100] := 4;  
ljbprog[101] := 12;  
ljbprog[102] := 2;  
ljbprog[103] := 1;  
ljbprog[104] := 10;  
ljbprog[105] := 2;  
ljbprog[106] := 4;  
ljbprog[107] := 13;  
ljbprog[108] := 2;  
ljbprog[109] := 1;  
ljbprog[110] := 12;  
ljbprog[111] := 2;  
ljbprog[112] := 1;  
ljbprog[113] := 10;  
ljbprog[114] := 4;  
ljbprog[115] := 2;  
ljbprog[116] := 1;  
ljbprog[117] := 13;  
ljbprog[118] := 3;  
ljbprog[119] := 5;  
ljbprog[120] := 7;  
ljbprog[121] := 0;  
ljbprog[122] := 1;  
ljbprog[123] := 0;  
ljbprog[124] := 0;
```

```

ljbprog[125] := 5;
ljbprog[126] := 13;
ljbprog[127] := 9;
ljbprog[128] := 14;
ljbprog[129] := 0;
ljbprog[130] := 0;
ljbprog[131] := 0;
ljbprog[132] := 0;
tempprog := 0;
end; {initvalues}

function dologic(funcnt, left, right: integer): integer;
const mask = 2147483647;
var value : integer;
begin
  value := 0;
  case funcnt of
    0 : value := 0;
    1 : value := right;
    2 : value := left;
    3 : value := mask - left;
    4 : value := left + right;
    5 : value := left - right;
    6 : while (right > 0) and (left <> 0) do begin
        left := land(left + left, mask);
        value := left;
        right := right - 1;
      end;
    7 : value := left * right;
    8 : value := land(left, right);
    9 : value := left + right - land(left, right);
    10: value := left + right - land(left, right) * 2;
    11: value := 0;
    12: if left = right then value := 1;
    13: if left < right then value := 1
  end; {case}
  dologic := value;
end; {dologic}

function sinput(address: integer): integer;
var datum: char;
  data: integer;
begin
  if address = 0 then begin
    read(input, datum);
    sinput := ord(datum)
  end
  else if address = 1 then begin
    read(input, data);
    sinput := data
  end
  else begin

```

```

        write(output, 'Input from address ', address:1, ': ');
        readln(input, data);
        sinput := data;
    end
end; {sinput}

procedure soutput(address, data: integer);
begin
    if address = 0 then writeln(output, chr(data))
    else if address = 1 then writeln(output, data)
    else writeln(output, 'Output to address ', address:1,
        ': ', data:1)
    end; {soutput}

begin
    initvalues;
    cycles := 0;
    if cycles = 0 then begin
        writeln('Number of cycles to trace');
        read(cycles);
    end;
    cyclecount := 0;
    while cyclecount <= cycles do begin
    case land(tempstate, 63) of
        0 : ljbrom := 4184;
        1 : ljbrom := 256;
        2 : ljbrom := 256;
        3 : ljbrom := 256;
        4 : ljbrom := 288;
        5 : ljbrom := 256;
        6 : ljbrom := 256;
        7 : ljbrom := 256;
        8 : ljbrom := 296;
        9 : ljbrom := 256;
        10 : ljbrom := 143;
        11 : ljbrom := 1536;
        12 : ljbrom := 256;
        13 : ljbrom := 150;
        14 : ljbrom := 8326;
        15 : ljbrom := 576;
        16 : ljbrom := 256;
        17 : ljbrom := 256;
        18 : ljbrom := 396;
        19 : ljbrom := 16;
        20 : ljbrom := 320;
        21 : ljbrom := 2182;
        22 : ljbrom := 1792;
        23 : ljbrom := 320;
        24 : ljbrom := 320;
        25 : ljbrom := 0;
        26 : ljbrom := 0;
        27 : ljbrom := 0;

```

```

28 : ljbrom := 0;
29 : ljbrom := 0;
30 : ljbrom := 0;
31 : ljbrom := 4164;
32 : ljbrom := 0;
33 : ljbrom := 132;
34 : ljbrom := 196;
35 : ljbrom := 196;
36 : ljbrom := 132;
37 : ljbrom := 134;
38 : ljbrom := 134;
39 : ljbrom := 134;
40 : ljbrom := 256;
41 : ljbrom := 256;
42 : ljbrom := 134;
43 : ljbrom := 134;
44 : ljbrom := 32;
45 : ljbrom := 134;
46 : ljbrom := 134;
47 : ljbrom := 256;
48 : ljbrom := 0;
49 : ljbrom := 196;
50 : ljbrom := 134;
51 : ljbrom := 134;
52 : ljbrom := 2437;
53 : ljbrom := 131;
54 : ljbrom := 64;
55 : ljbrom := 0;
56 : ljbrom := 0;
57 : ljbrom := 0;
58 : ljbrom := 0;
59 : ljbrom := 0;
60 : ljbrom := 0;
61 : ljbrom := 0;
62 : ljbrom := 0;
63 : ljbrom := 0;
end;
ljbexit := dologic(land(ljbrom, 256) div 256 + 12, tempram,
                    land(ljbrom, 256) * 16);
case land(ljbrom, 1024) div 1024 of
  0 : ljbrelpc := tempram;
  1 : ljbrelpc := 0;
end;
case land(ljbrom, 512) div 512 of
  0 : ljboffset := 1;
  1 : ljboffset := templeft;
end;
ljbnewpc := ljbrelpc + ljboffset;
case land(ljbrom, 7) of
  0 : ljbpc := 0;
  1 : ljbpc := 0;
  2 : ljbpc := 0;

```

```

3 : ljbbsp := tempfp;
4 : ljbbsp := 1;
5 : ljbbsp := templeft;
6 : ljbbsp := 1;
7 : ljbbsp := tempright;
end;
ljbpushpop := dologic(land(ljbrom, 2) div 2 + land(ljbrom,
4), tempfp, ljbbsp);
case land(tempir, 1) of
0 : ljbselfp := tempfp;
1 : ljbselfp := tempram;
end;
ljbafp := tempfp + templeft;
case land(ljbrom, 32) div 32 of
0 : ljbaddr := tempfp;
1 : ljbaddr := ljbafp;
end;
ljbneg := 0 - tempram;
case land(tempstate, 63) of
0 : ljbparm := 0;
1 : ljbparm := 0;
2 : ljbparm := 387;
3 : ljbparm := 160;
4 : ljbparm := 25;
5 : ljbparm := 0;
6 : ljbparm := 224;
7 : ljbparm := 6;
8 : ljbparm := 9;
9 : ljbparm := 192;
10 : ljbparm := 11;
11 : ljbparm := 0;
12 : ljbparm := 0;
13 : ljbparm := 4;
14 : ljbparm := 15;
15 : ljbparm := 25;
16 : ljbparm := 416;
17 : ljbparm := 432;
18 : ljbparm := 9;
19 : ljbparm := 8;
20 : ljbparm := 433;
21 : ljbparm := 10;
22 : ljbparm := 96;
23 : ljbparm := 436;
24 : ljbparm := 407;
25 : ljbparm := 0;
26 : ljbparm := 18;
27 : ljbparm := 14;
28 : ljbparm := 13;
29 : ljbparm := 7;
30 : ljbparm := 5;
31 : ljbparm := 0;
32 : ljbparm := 31;

```

```

33 : ljbparm := 1;
34 : ljbparm := 2;
35 : ljbparm := 2;
36 : ljbparm := 12;
37 : ljbparm := 30;
38 : ljbparm := 29;
39 : ljbparm := 29;
40 : ljbparm := 0;
41 : ljbparm := 224;
42 : ljbparm := 30;
43 : ljbparm := 30;
44 : ljbparm := 12;
45 : ljbparm := 28;
46 : ljbparm := 27;
47 : ljbparm := 32;
48 : ljbparm := 0;
49 : ljbparm := 24;
50 : ljbparm := 26;
51 : ljbparm := 19;
52 : ljbparm := 64;
53 : ljbparm := 21;
54 : ljbparm := 22;
55 : ljbparm := 0;
56 : ljbparm := 0;
57 : ljbparm := 0;
58 : ljbparm := 0;
59 : ljbparm := 0;
60 : ljbparm := 0;
61 : ljbparm := 0;
62 : ljbparm := 0;
63 : ljbparm := 0;
end;
case land(tempir, 15) of
0 : ljbop := 0;
1 : ljbop := 0;
2 : ljbop := 1;
3 : ljbop := 4;
4 : ljbop := 1;
5 : ljbop := 8;
6 : ljbop := 13;
7 : ljbop := 12;
8 : ljbop := 3;
9 : ljbop := 0;
10 : ljbop := 4;
11 : ljbop := 7;
12 : ljbop := 2;
13 : ljbop := 1;
14 : ljbop := 12;
15 : ljbop := 5;
end;
case land(ljbparm, 32) div 32 of
0 : ljbseir := tempright;

```

```

1 : ljbseir := tempfp;
end;
ljbalu := dologic(ljbop, tempram, ljbseir);
case land(ljbexit, 1) + land(ljbrom, 12288) div 2048 of
0 : ljbnewst := land(ljbparm, 31);
1 : ljbnewst := land(ljbparm, 31);
2 : ljbnewst := land(tempprog, 15) + land(ljbrom, 4) * 4 +
32;
3 : ljbnewst := land(tempprog, 15) + land(ljbrom, 4) * 4 +
32;
4 : ljbnewst := 0;
5 : ljbnewst := land(ljbparm, 31);
6 : ljbnewst := 0;
7 : ljbnewst := land(tempprog, 15) + land(ljbrom, 4) * 4 +
32;
end;
case land(ljbparm, 224) div 32 of
0 : ljbwrite := ljbalu;
1 : ljbwrite := ljbalu;
2 : ljbwrite := tempfp;
3 : ljbwrite := temppc;
4 : ljbwrite := land(tempir, 1);
5 : ljbwrite := land(tempdata, 15) + land(tempram, 4095) *
16;
6 : ljbwrite := templeft;
7 : ljbwrite := ljbneg;
end;
write('Cycle ', cyclecount:3);
writeln;
adrstate := 0;
datastate := tempstate;
opnstate := 1;
adrpc := 0;
datapc := temppc;
opnpc := land(ljbrom, 64) div 64;
adrsp := 0;
datasp := tempsp;
opnsp := land(ljbrom, 128) div 128;
adrfp := 0;
datafp := tempfp;
opnfp := land(ljbrom, 2048) div 2048;
adrleft := 0;
dataleft := templeft;
opnleft := land(ljbrom, 8) div 8;
adrright := 0;
dataright := tempright;
opnrigh := land(ljbrom, 16) div 16;
adrir := 0;
datair := tempir;
opnir := land(ljbrom, 4096) div 4096;
adrdata := 0;
datadata := tempdata;

```

```

opndata := land(ljbparm, 256) div 256;
addram := land(ljbaddr, 4095);
dataram := tempram;
opnram := land(ljbram, 256) div 256 + land(ljbaddr, 4096)
div 2048;
adrprog := temppc;
dataprog := tempprog;
opnprog := 0;
tempstate := ljbnewst;
ljbstate[adrstate] := tempstate;
case land(opnpc, 3) of
  0: temppc := ljbpc[adrpc];
  1: begin
    temppc := ljbnewpc;
    ljbpc[adrpc] := temppc;
  end;
  2: temppc := sinput(adrpc);
  3: begin
    temppc := ljbnewpc;
    soutput(adrpc, temppc);
  end
end; {case}
case land(opnsp, 3) of
  0: tempsp := ljbsp[adrsp];
  1: begin
    tempsp := ljbpushpop;
    ljbsp[adrsp] := tempsp;
  end;
  2: tempsp := sinput(adrsp);
  3: begin
    tempsp := ljbpushpop;
    soutput(adrsp, tempsp);
  end
end; {case}
case land(opnfp, 3) of
  0: tempfp := ljbfp[adrfp];
  1: begin
    tempfp := ljbselfp;
    ljbfp[adrfp] := tempfp;
  end;
  2: tempfp := sinput(adrfp);
  3: begin
    tempfp := ljbselfp;
    soutput(adrfp, tempfp);
  end
end; {case}
case land(opnleft, 3) of
  0: templeft := ljbleft[adrleft];
  1: begin
    templeft := tempram;
    ljbleft[adrleft] := templeft;
  end;
end;

```

```

2: templeft := sinput(adrlft);
3: begin
    templeft := tempram;
    soutput(adrlft, templeft);
end
end; {case}
case land(opnright, 3) of
0: tempright := ljbright[adrright];
1: begin
    tempright := tempram;
    ljbright[adrright] := tempright;
end;
2: tempright := sinput(adrright);
3: begin
    tempright := tempram;
    soutput(adrright, tempright);
end
end; {case}
case land(opnir, 3) of
0: tempir := ljbir[adrir];
1: begin
    tempir := tempprog;
    ljbir[adrir] := tempir;
end;
2: tempir := sinput(adrir);
3: begin
    tempir := tempprog;
    soutput(adrir, tempir);
end
end; {case}
case land(opndata, 3) of
0: tempdata := ljbdata[adrdata];
1: begin
    tempdata := tempprog;
    ljbdata[adrdata] := tempdata;
end;
2: tempdata := sinput(adrdata);
3: begin
    tempdata := tempprog;
    soutput(adrdata, tempdata);
end
end; {case}
case land(opnram, 3) of
0: tempram := ljbram[adrram];
1: begin
    tempram := ljbwrite;
    ljbram[adrram] := tempram;
end;
2: tempram := sinput(adrram);
3: begin
    tempram := ljbwrite;
    soutput(adrram, tempram);
end
end; {case}

```

```
        end
end; {case}
tempprog := ljbprog[adrprog];
cyclecount := cyclecount + 1;
if cyclecount = cycles + 1 then begin
    writeln('Continue to cycle (0 to quit)');
    read(cycles);
end;
end; {while}
end.
```

Appendix F

Example of specification translation to a hardware diagram

Specification in ASIM II

```
# tiny computer specification 1986 June 12

{macro definition of instructions}
~LD 256 ~ST 384 ~BB 512 ~BR 640 ~SU 768

state* nextstate phase pc* incpc newpc ir decode ma
memory ac* borrow alu sel sell b2 sub.

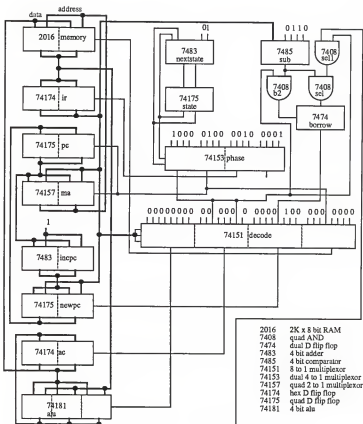
M state 0 nextstate.0.1 1 1 {state counter}
A nextstate %0100 state 1
S phase state.0.1 %0001 %0010 %0100 %1000
A incpc %0100 pc 1 {add pc+1 (or load ir) in
                    phase.2}
S newpc decode.1 incpc ir
M pc 0 newpc.0.6 phase.2 1
M ir 0 memory phase.1 1
S decode ir.7.9
  0
  0
  phase.3,#00
  phase.2
  borrow,#0
  #10 {unconditional only}
  1,phase.3,#00
  0
A alu decode.3,#01 ac memory.0.9 {subtract or load}
M ac 0 alu.0.10 decode.2 1
M borrow 0 sel b2 1 {borrow flag set only on
                    subtract}
```

```

A b2 8 phase.3 sub      {operation and during phase 3}
A sub 12 %110 ir.7.9    {is this a subtract operation?}
A sel 8 sub sell        { select based on subtract
                        operation and}
A sell 8 alu.10 phase.3 {phase 3 and bit 10 of alu}
S ma phase.2 pc ir
M memory ma.0.6 ac decode.0 -128
{decimal memory data follows}
~LD+30    {load accumulator from location 30}
~SU+31    {subtract value in location 31 from
          accumulator}

~LD+30
~SU+32
~LD+32
~SU+30
~LD+34
~SU+33
~LD+30
~SU+31
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0
5 7 7 10 5
0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

```



COMPUTER ARCHITECTURE SIMULATION
USING A REGISTER TRANSFER LANGUAGE

by

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ABSTRACT

ASIM II (Architecture Simulator II) is a compiler which compiles an electronic hardware description to Pascal. When executed, this Pascal code simulates the hardware described in the specification. The components of an electronic system are described by three primitives: ALU, selector, and memory. These three primitives are sufficient to describe any piece of digital electronic equipment and resemble their hardware counterparts in a digital electronic system. ASIM II is different from other computer hardware description languages in that it uses only these three primitives. It is not based upon an underlying programming language on which it is implemented, or on a more complex set of primitives. ASIM II significantly reduces the simulation time over an interpreter while maintaining the same functionality.